

Batteries and Actuators

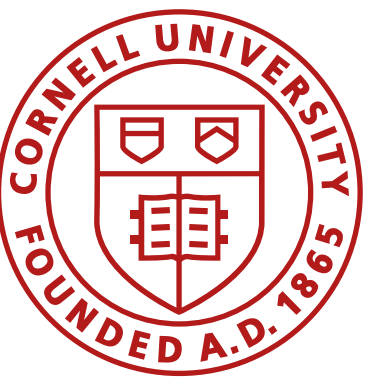
Fast Robots, ECE4160/5160, MAE 4190/5190

E. Farrell Helbling, 2/5/26

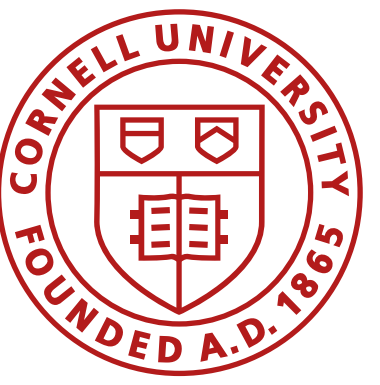
Slides adapted from Prof. Kirstin Petersen

Clarifications

- Some confusion about your write up submissions
 - Do not submit anything to canvas
 - Update your GitHub page and post your write up before the deadline (8am Tuesday/Wednesday).
 - If you need until 8:30/9am to finish something because there was a bug, this is fine. You do not need to email me. If you regularly do this, we will start to use your extensions.
 - We can use your github repository to determine what your page looked like at the deadline. We will use that to grade your work. Or dock you an extension.
 - If you want to use an extension, please send the teaching team a private message on Ed.
 - This class moves quickly and builds, meeting deadlines is important.
- Also, do not use the maker spaces for coursework.



(Rechargeable) batteries

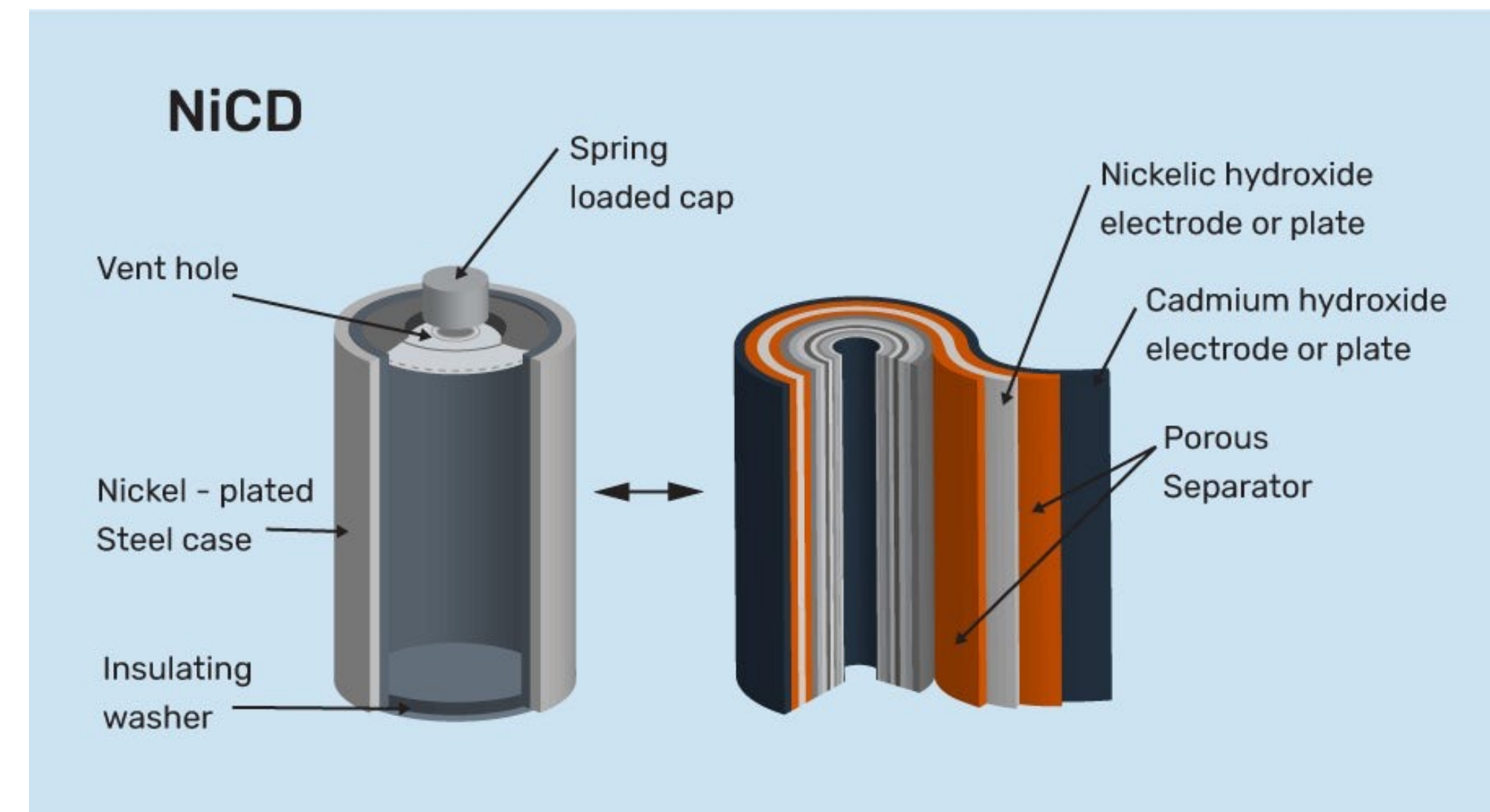


Important properties

What to look for when choosing a battery?

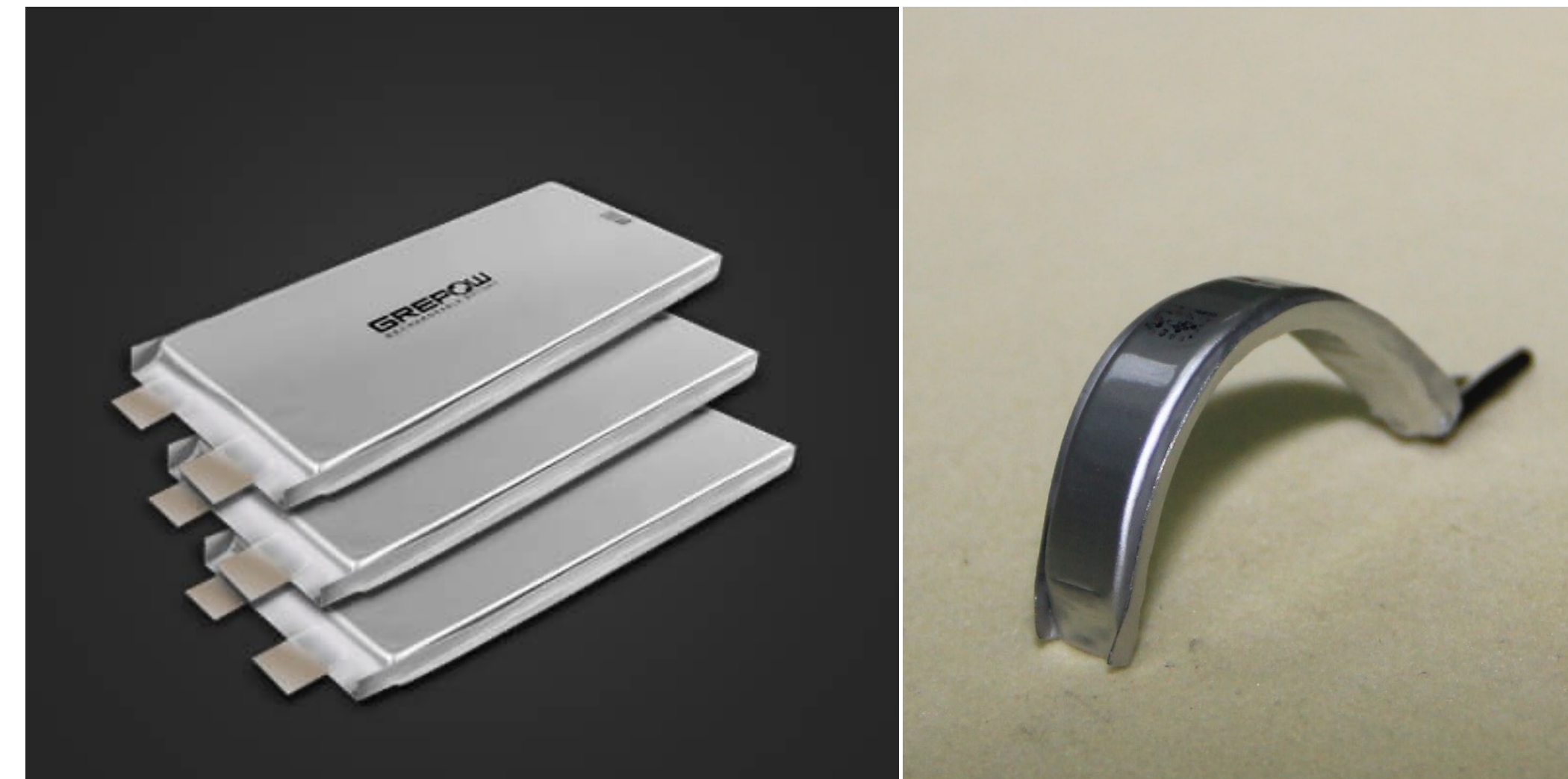
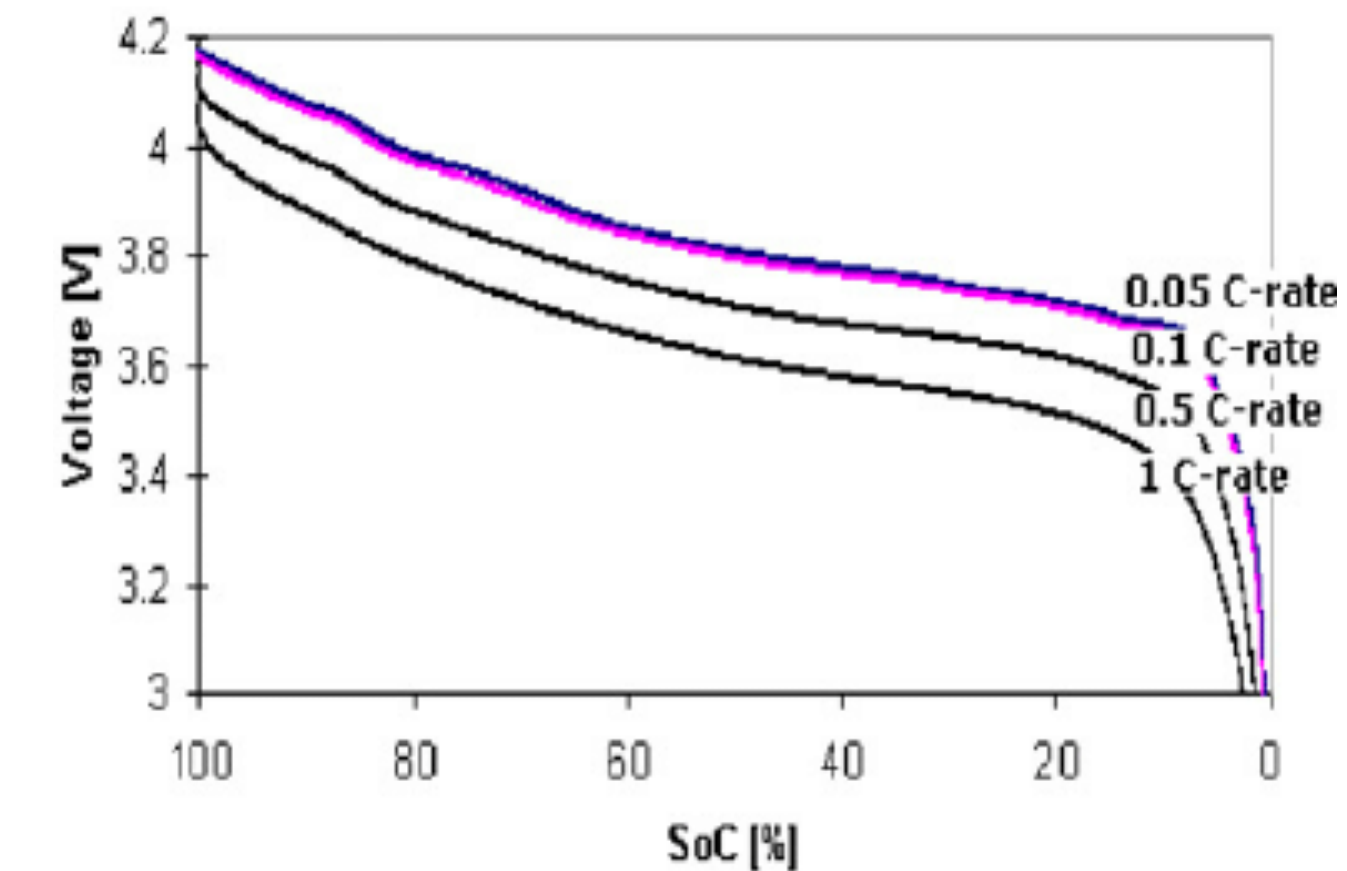
Rechargeable Batteries

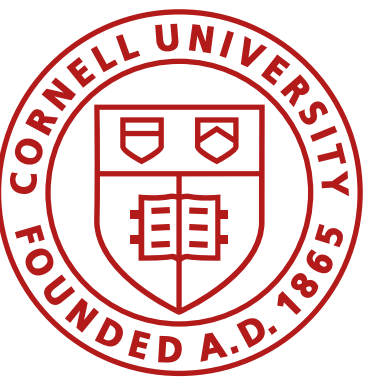
- Lead Acid (SLA)
 - Cheap
 - Large power applications
 - Low energy density
- Nickel Cadmium (NiCd)
 - Mature tech, affordable
 - Fairly low in energy density
 - High discharge rate
 - Long cycle life
 - Better in rigorous working conditions
 - Periodic full discharge/ charge is critical
 - Contains toxic metals
- Nickel-metal Hydride (NiMH)
 - Higher capacity/ energy density than NiCd
 - Medium discharge rate
 - More robust
 - Reduced cycle life
 - No toxic metals
 - More expensive than NiCd



Rechargeable Batteries

- Lithium Ion (li-ion)
 - High energy density
 - Lightweight
 - Low-maintenance battery
 - Low self-discharge
 - Max discharge rate: 1-2C
 - High cell voltage (single cell batteries)
 - Form factor: prismatic and cylindrical
 - Protection circuits for charge/ discharge
 - Aging, safety concerns
 - Lithium Polymer (li-po)
 - Lightweight
 - Free form-factor
 - Less safety concerns (dry/gel electrolyte)
 - Max discharge rate: 3-60C
 - Lower energy density than Li-ion
 - Costs more than Li-ion
- What is this?**



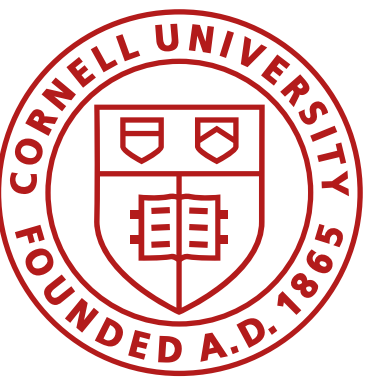


Lithium and Cobalt

- Lithium is an extremely important commodity
 - Renewable energy storage, EVs, batteries
 - 80% is mined in Australia, Chile, and China
 - China controls ~50% of processing and refining
 - US mines and processes 1% (environmental concerns)
- Cobalt is used for the electrolytes
 - 70% of the world's Cobalt comes from the DRC
 - China has the largest footprint in critical minerals and infrastructure in Africa



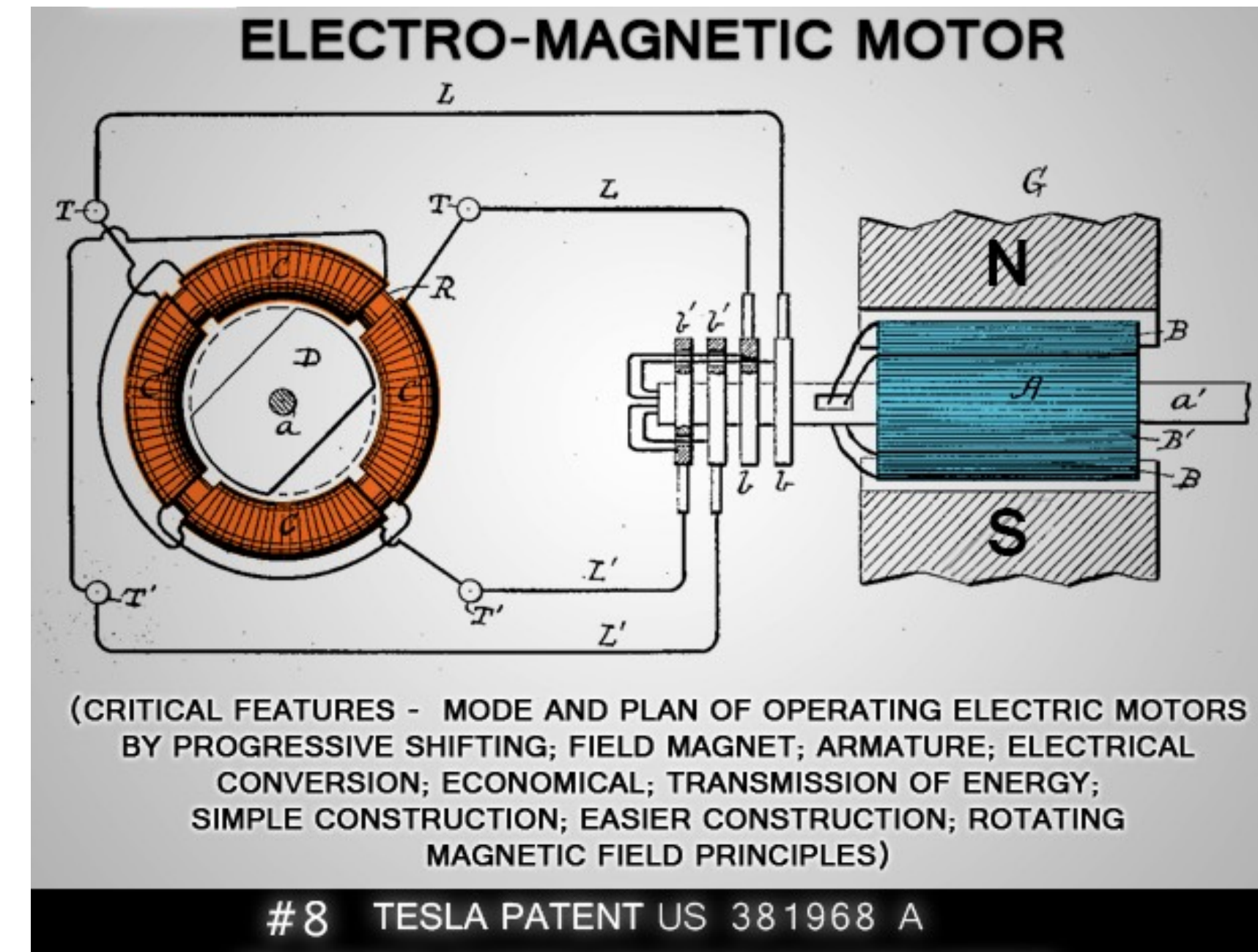
Cobalt electrolytic and 1cm³ cube



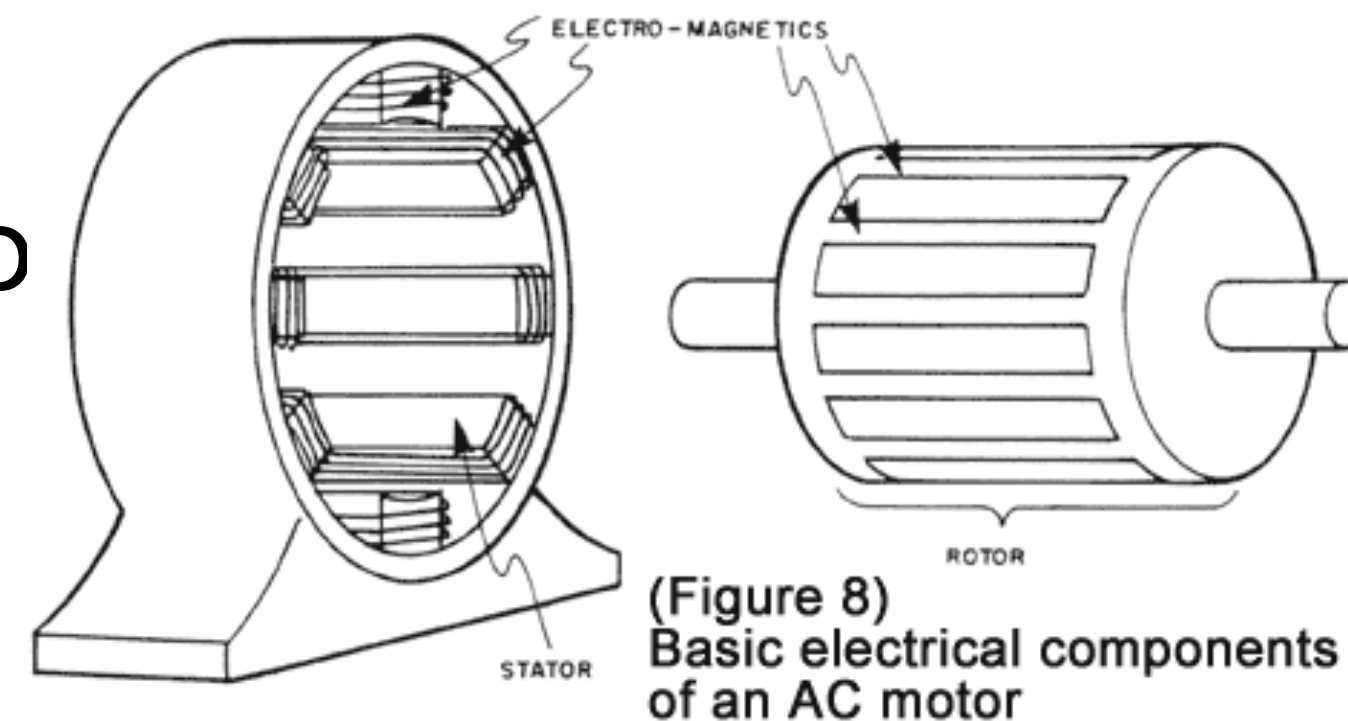
Electric motors

AC Motors

- High power/ torque
- Access to a mains/wall outlet
- Synchronous AC motors
 - Rotor turns as fast as the magnetic field fluctuates
- Asynchronous AC motors/ induction motors
 - Rotor turns slower than the field
 - Coil, frequency, and load dependent
- Simple, low cost, long lasting
- You'll need a variable frequency drive to change speed

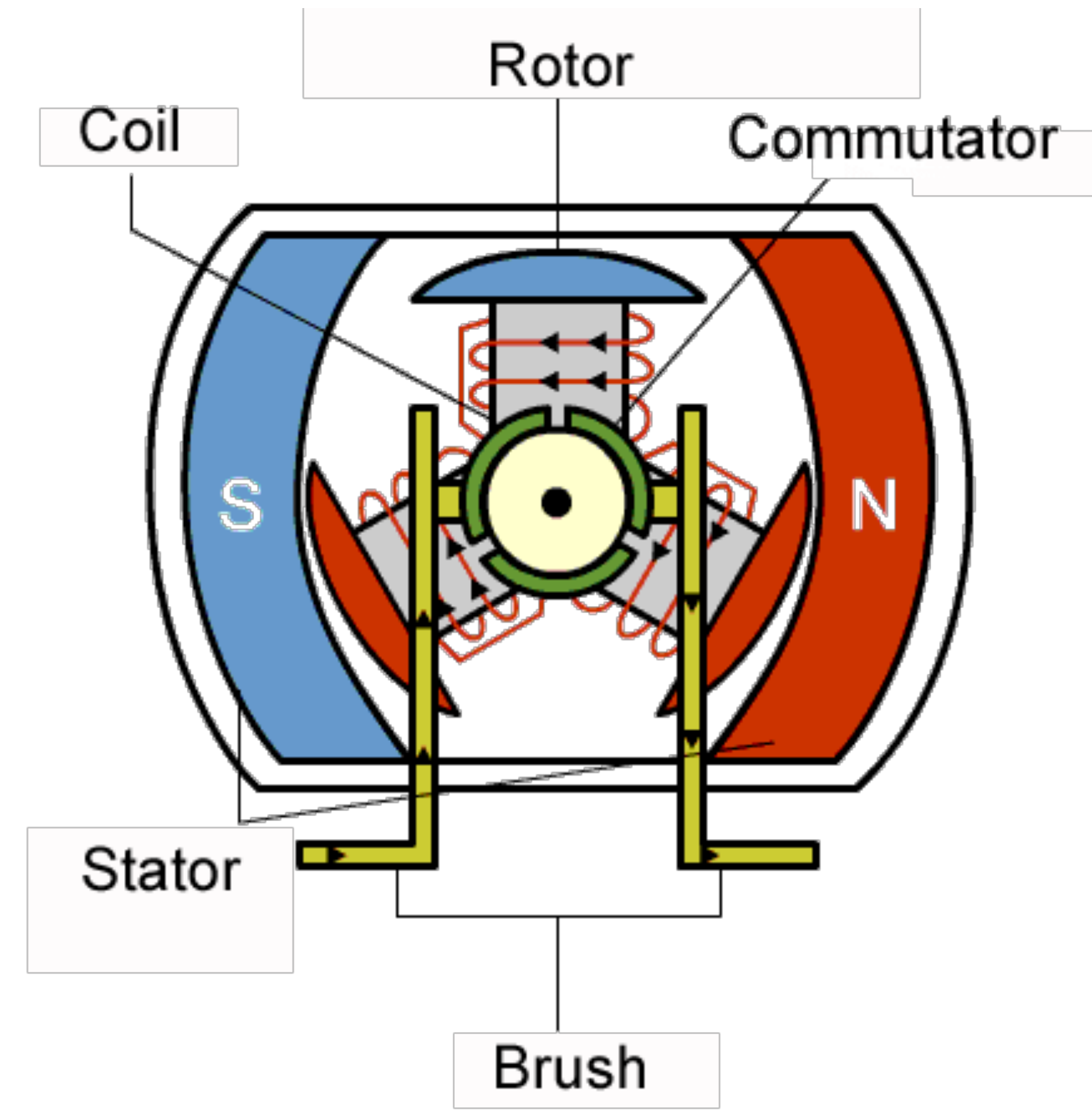


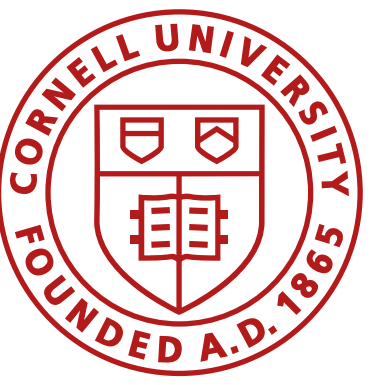
<https://www.explainthatstuff.com/induction-motors.html>



Brushed DC motor

- Brushes conduct current from source to armature
- Most commonly permanent magnet DC motors (PMDC)
- Pros
 - Inexpensive
 - Easy speed control (DC voltage)
 - Lightweight
 - Reasonably efficient
 - Great for low power, low form factor apps
- Cons
 - Mechanical wear
 - Electrical noise
 - Gearing is often needed



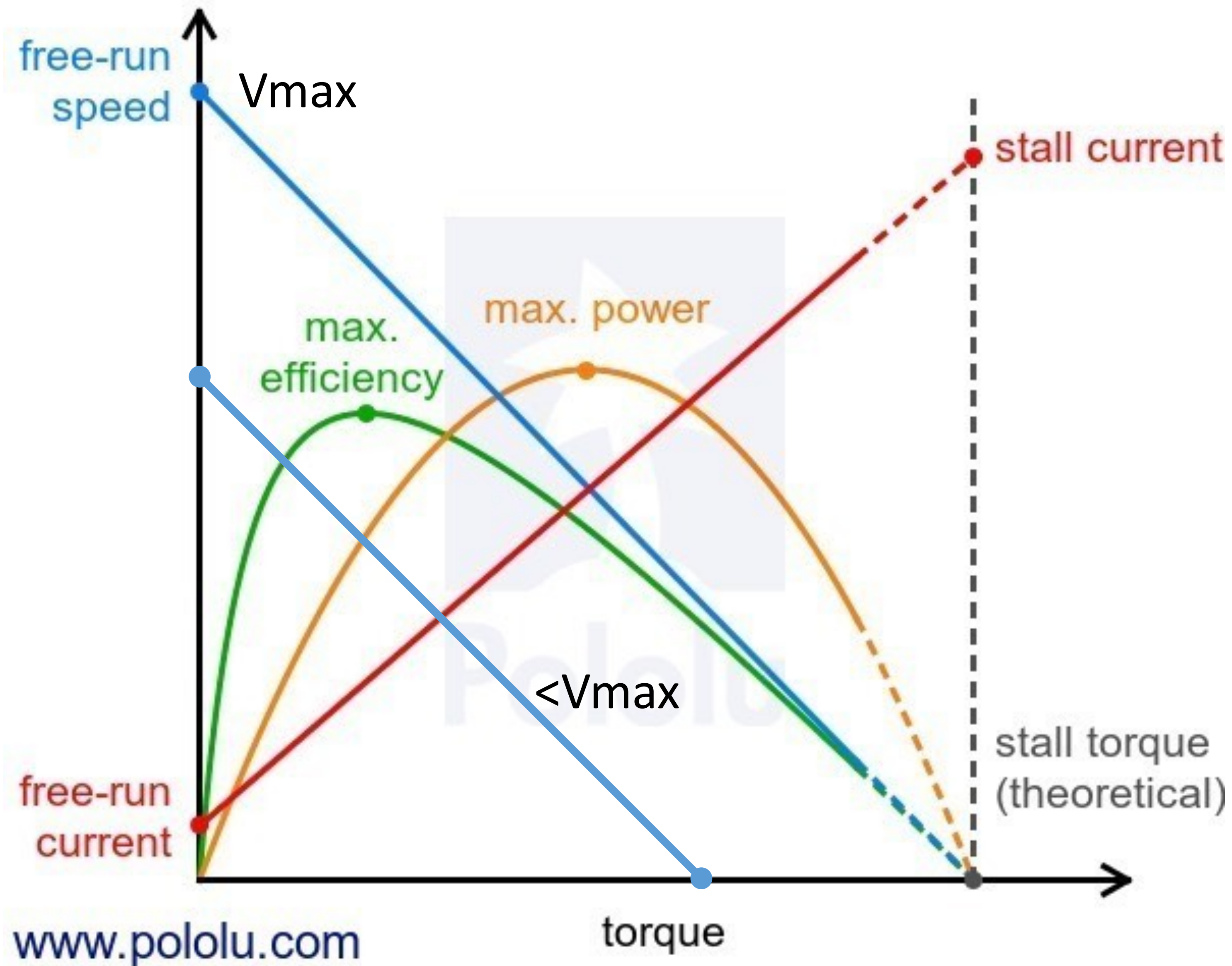


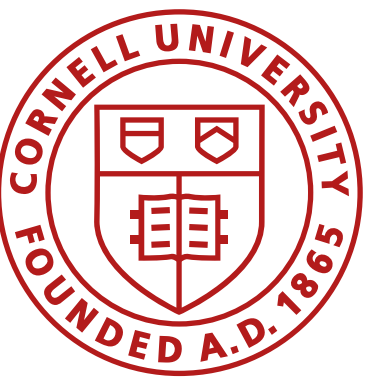
Brushed DC motor

Power = Torque x speed



3VDC	0kgcm	150mA	120RPM
3VDC	0.4kgcm	1.1A	0RPM
6VDC	0kgcm	160mA	250RPM
6VDC	0.8kgcm	1.5A	0RPM





Brushed DC motor controllers

DRV8833 Dual Motor Driver Carrier

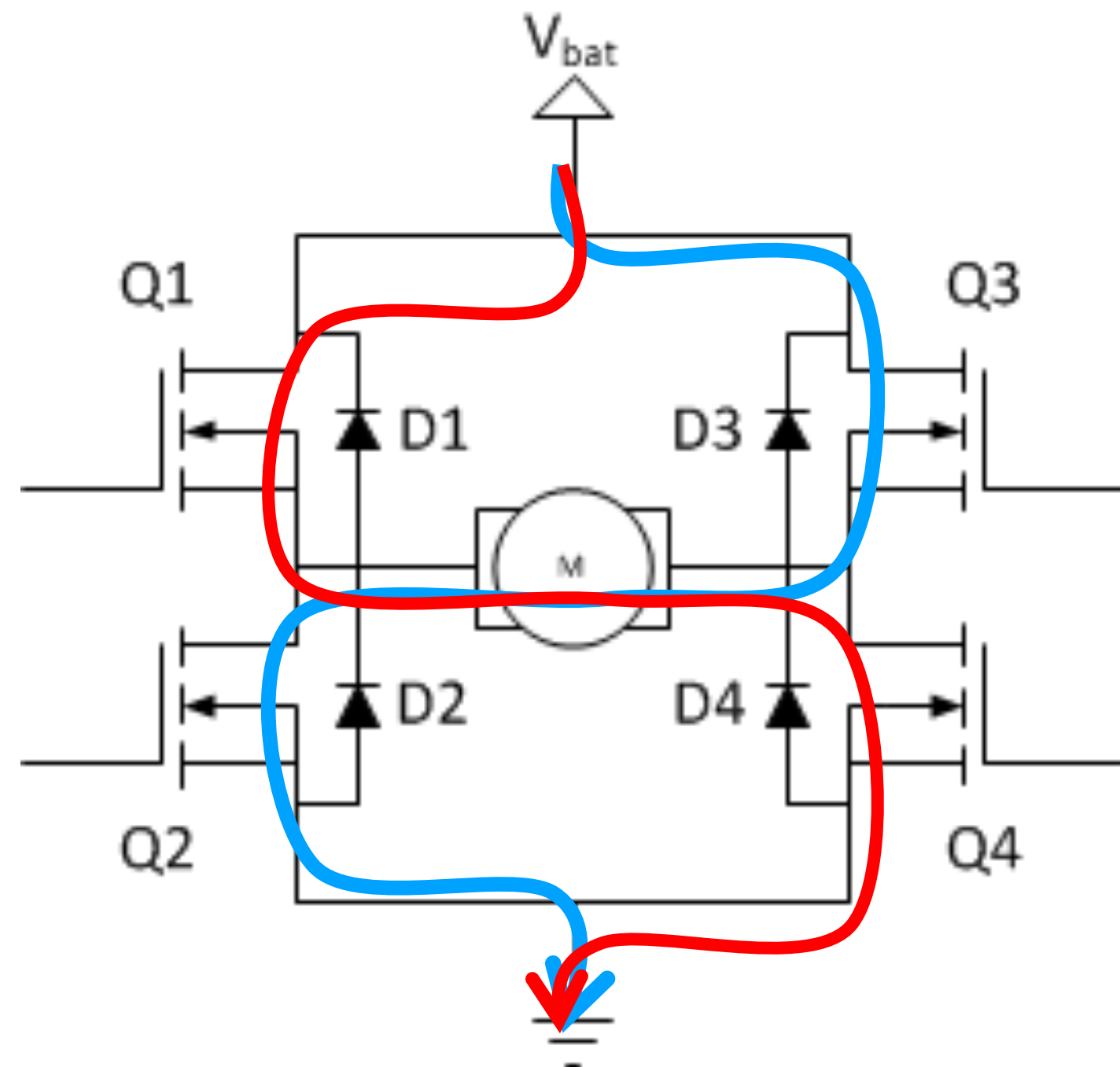
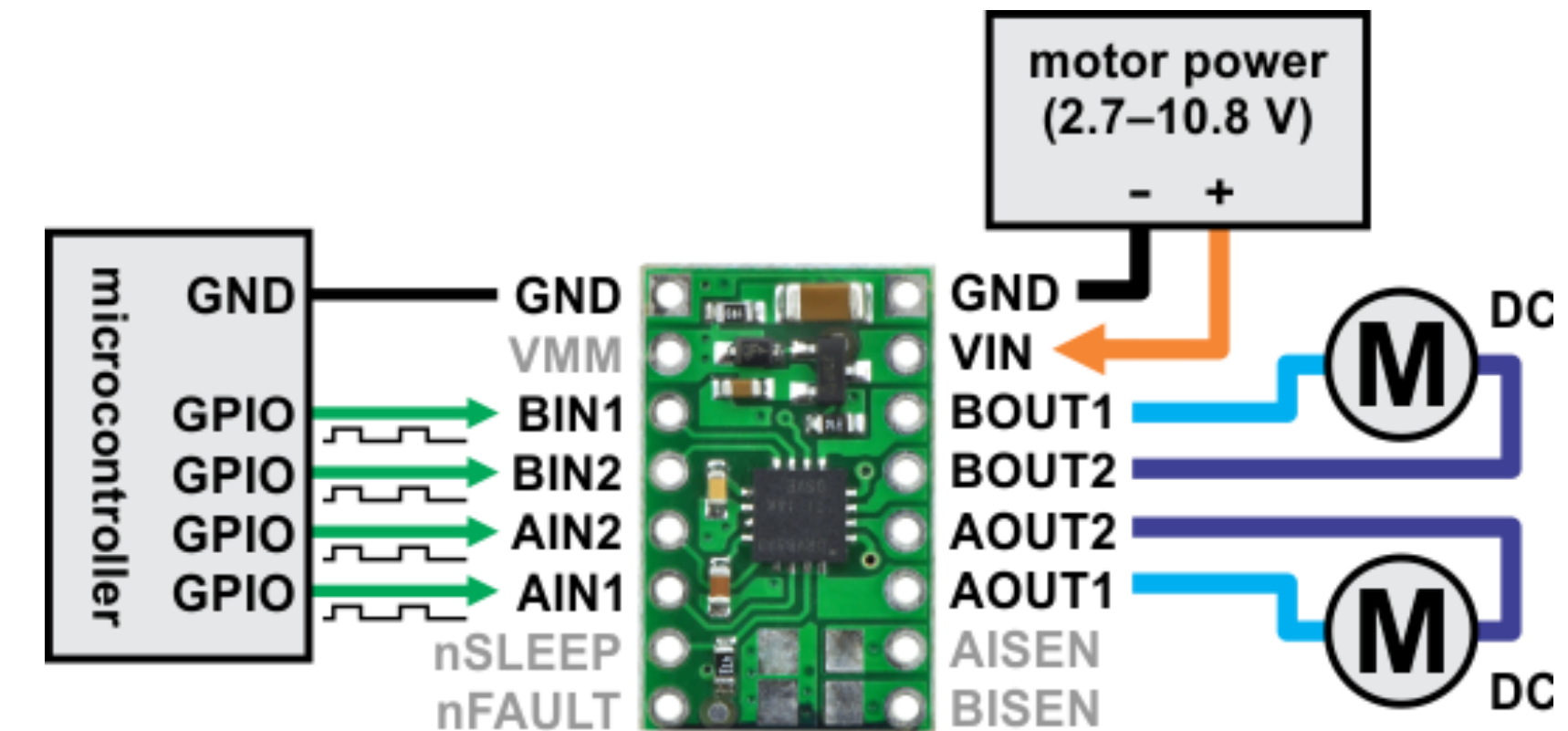
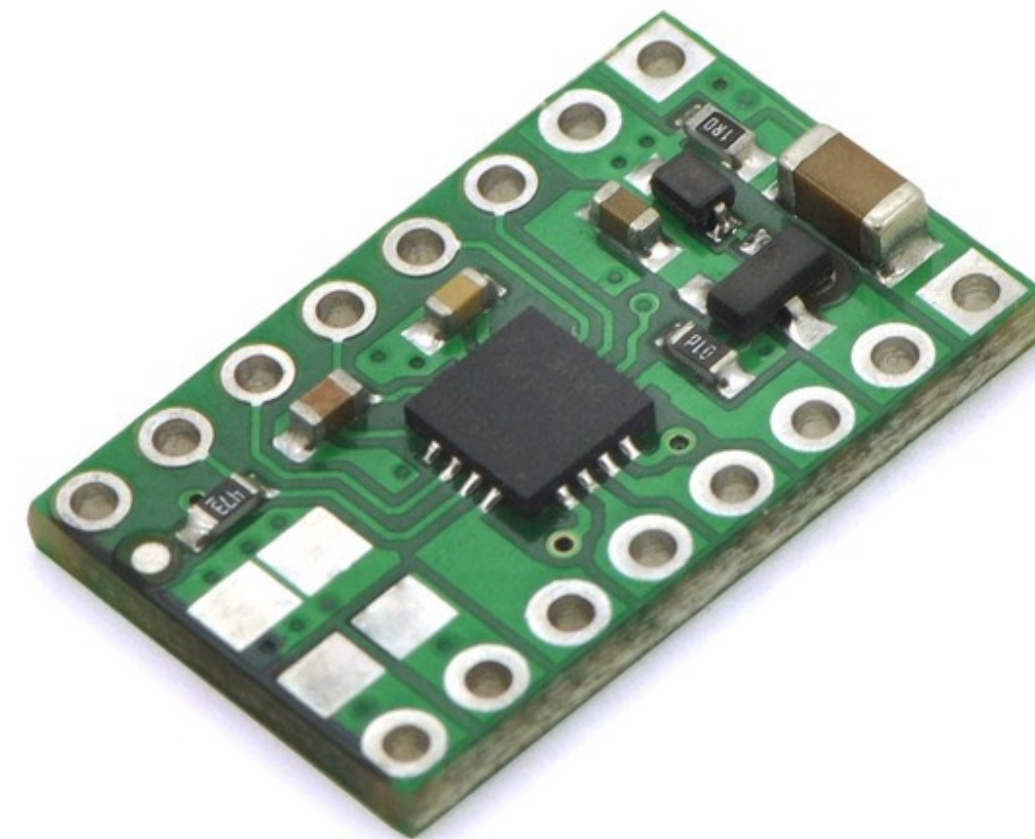
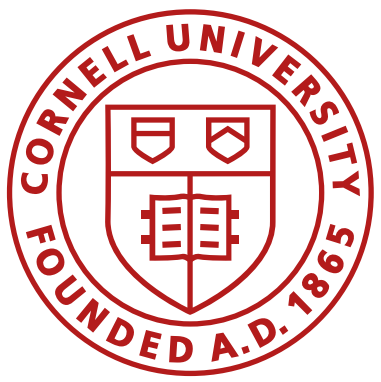


Table 1. H-Bridge Logic

xIN1	xIN2	xOUT1	xOUT2	FUNCTION
0	0	Z	Z	Coast/fast decay
0	1	L	H	Reverse
1	0	H	L	Forward
1	1	L	L	Brake/slow decay



Brushed DC motor controllers

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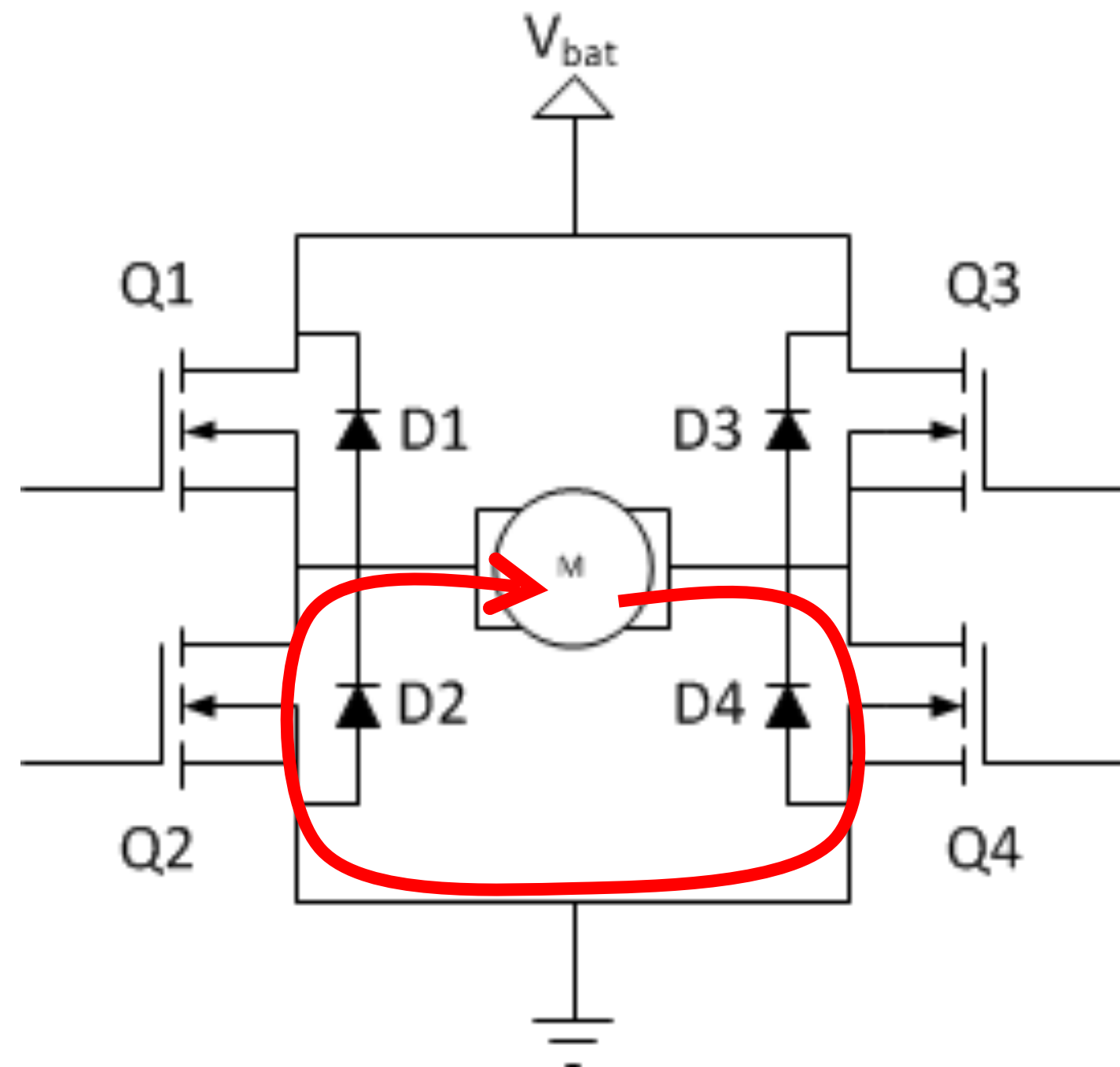
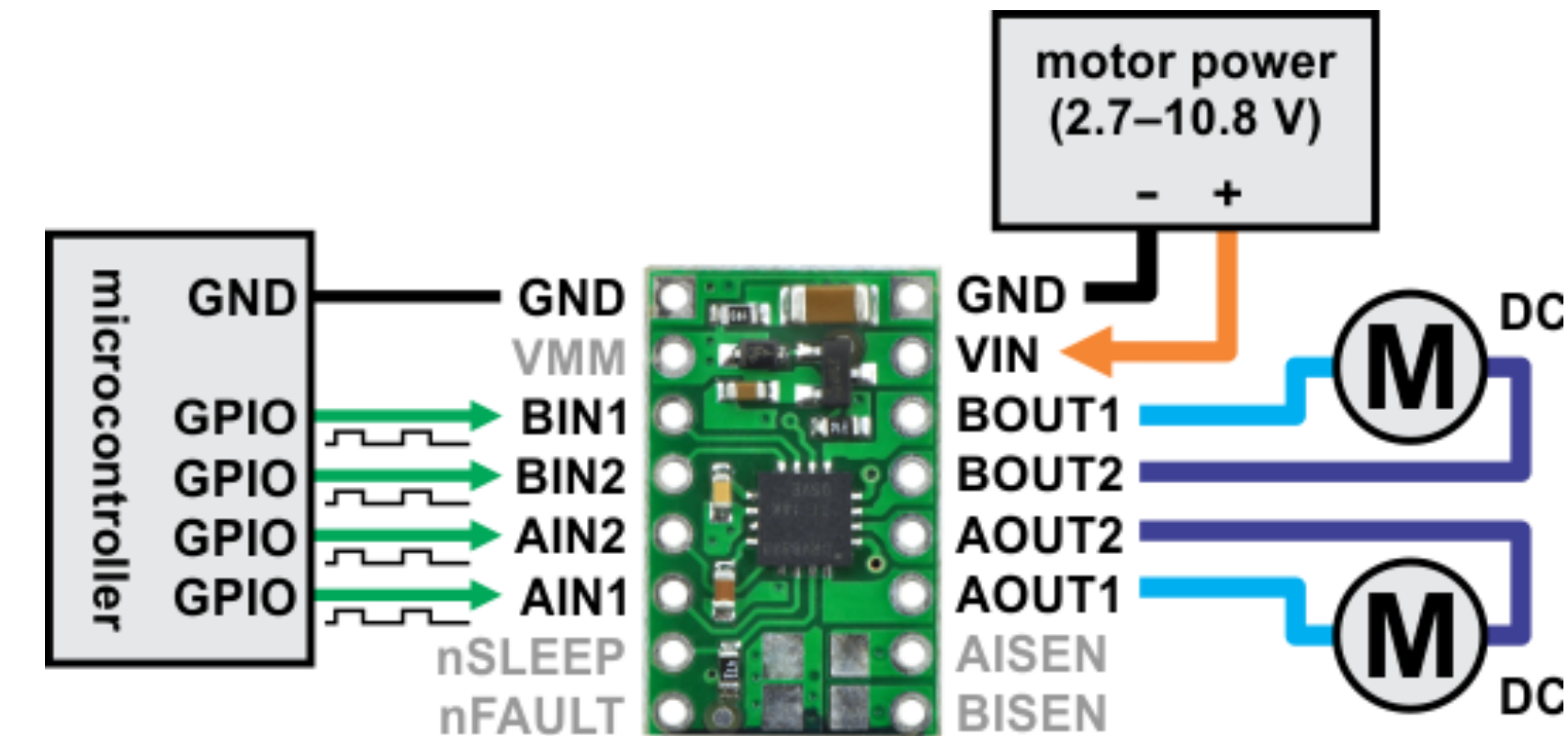
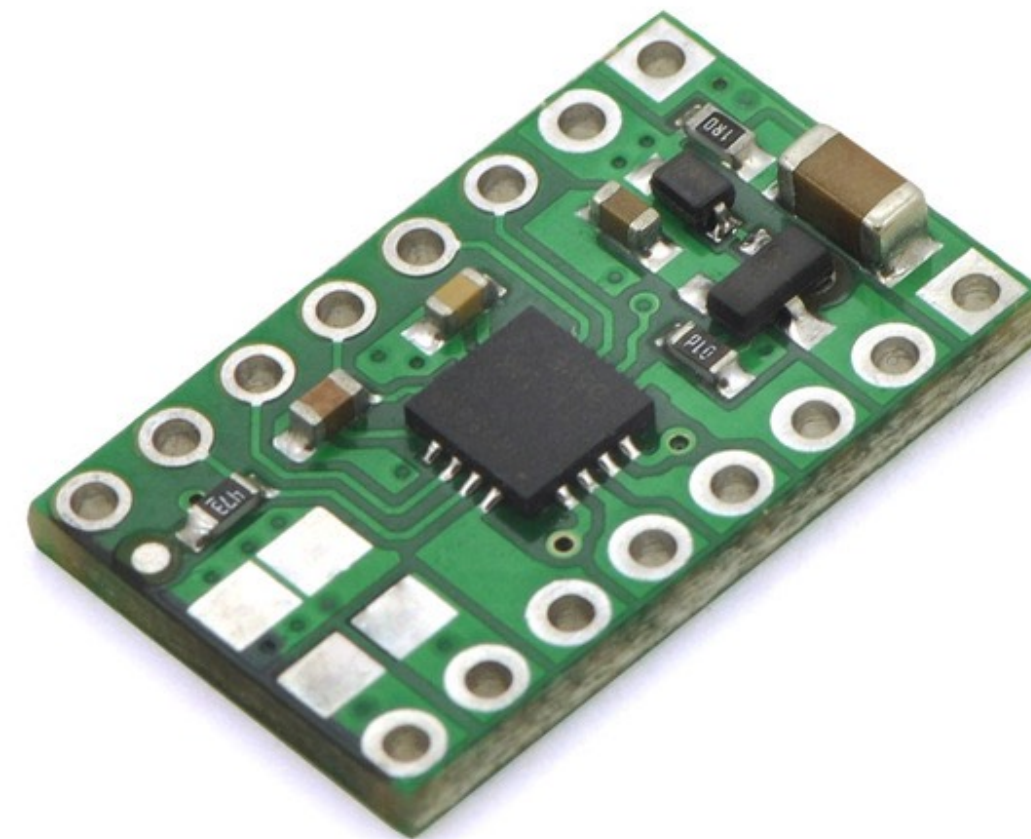
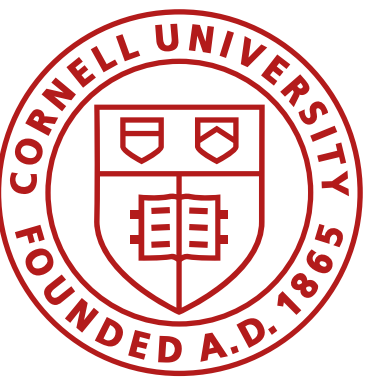


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Brushed DC motor controllers

DRV8833 Dual Motor Driver Carrier

Why do we have flyback diodes?

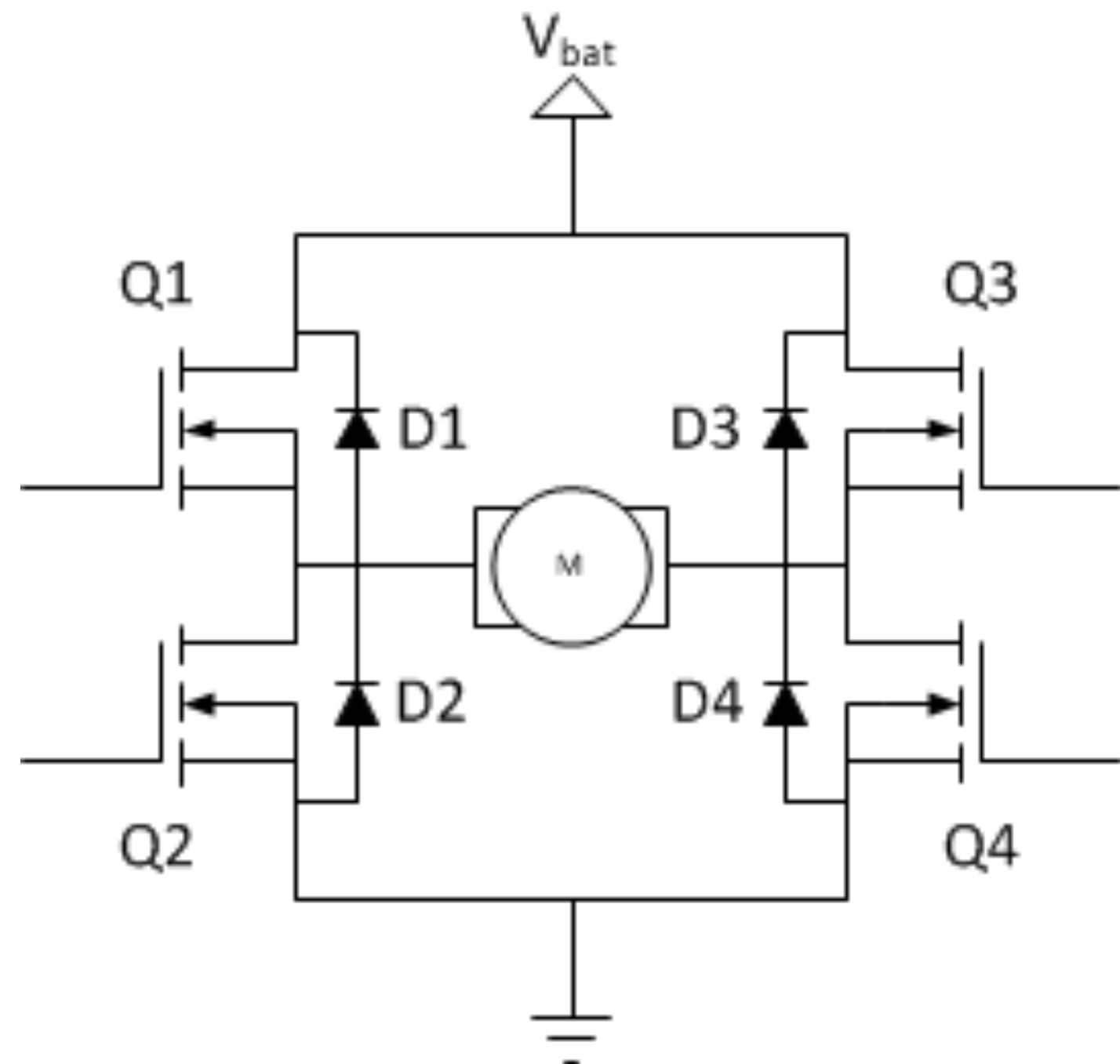
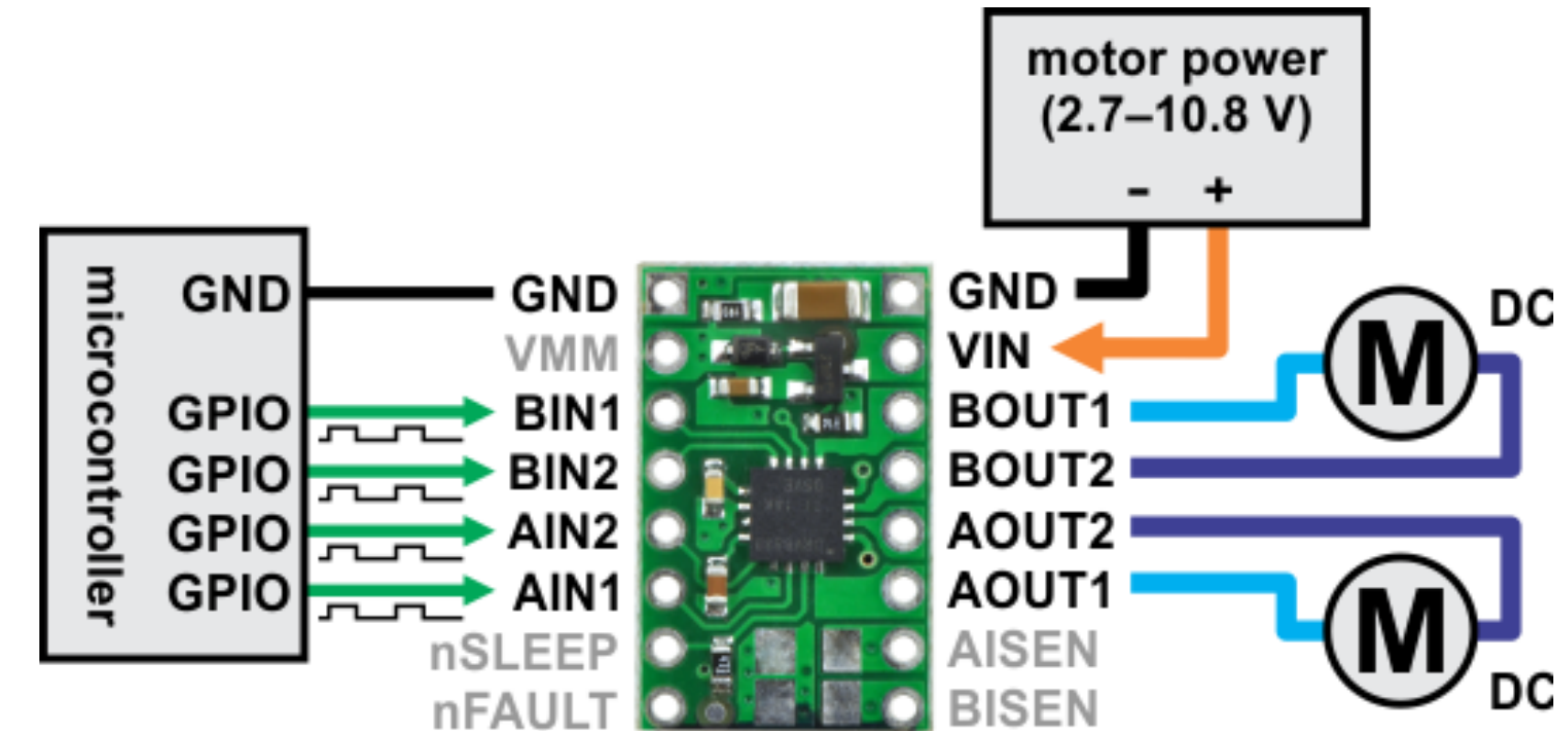
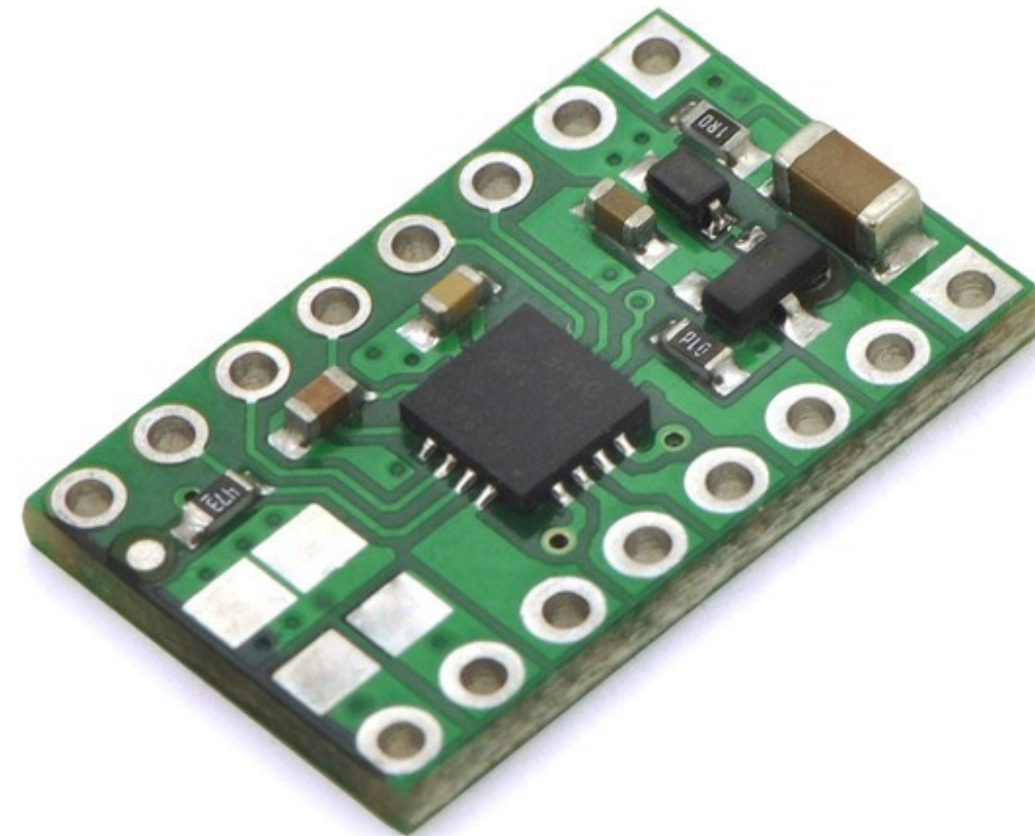
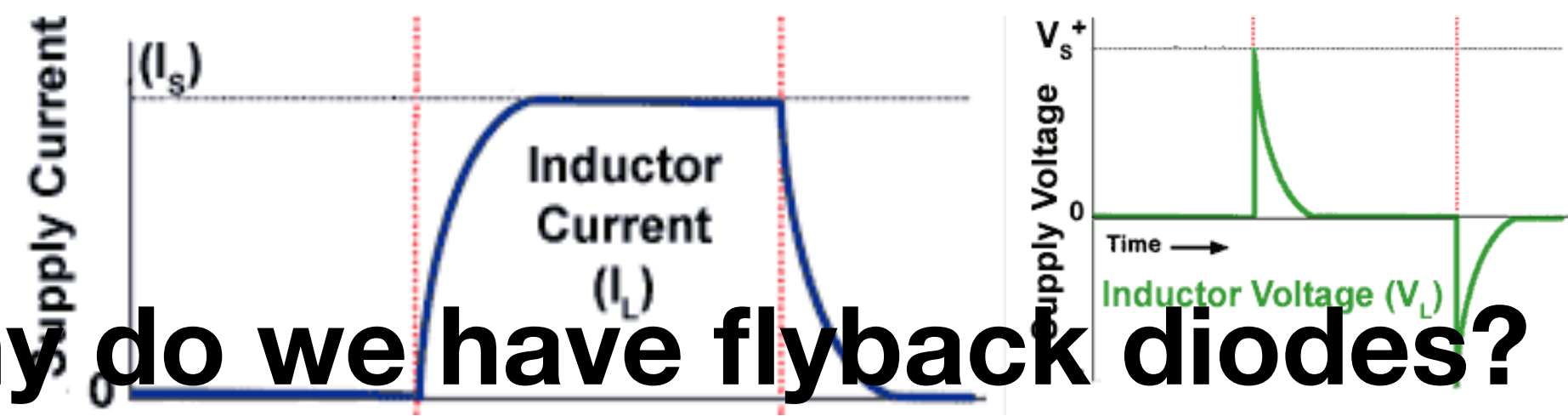
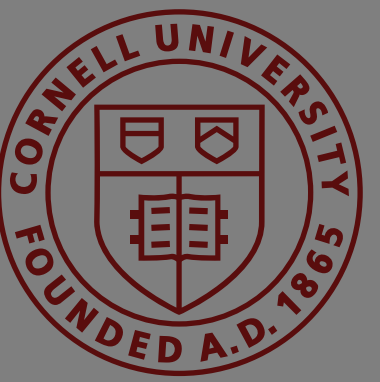


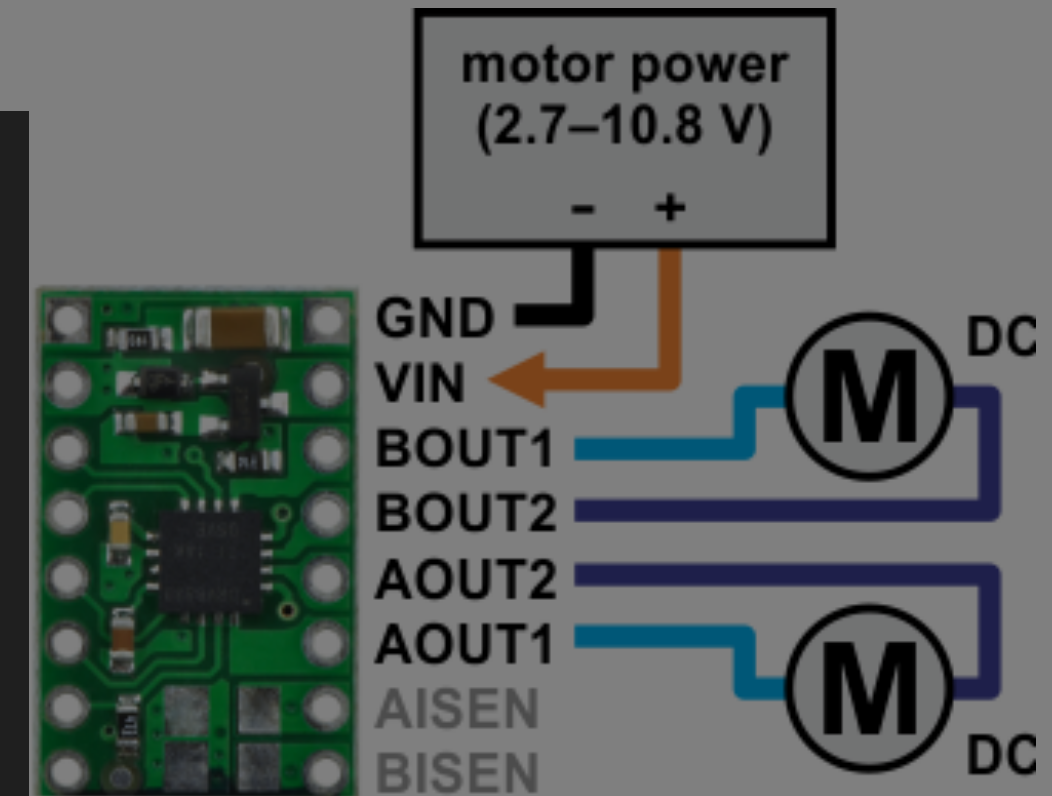
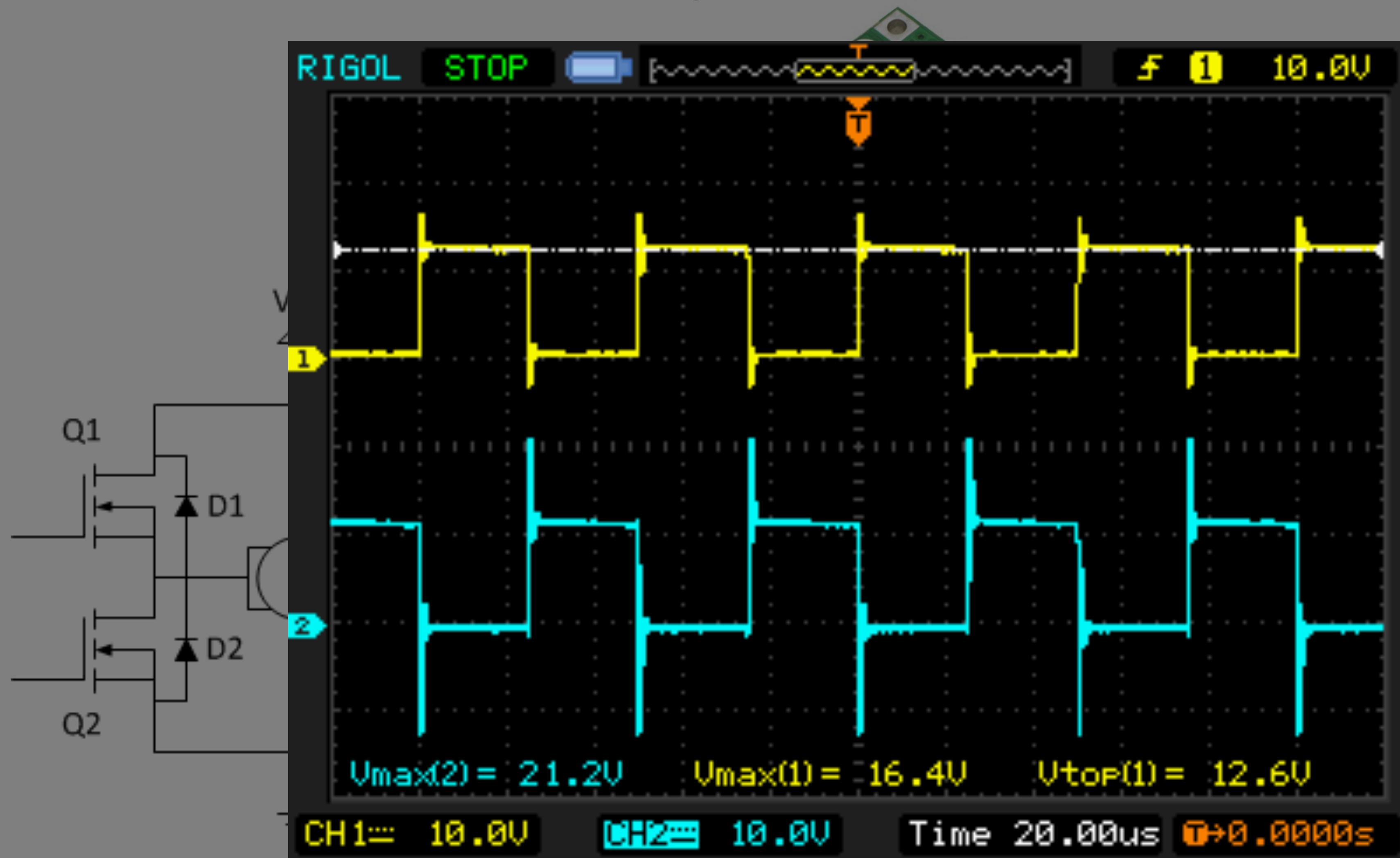
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Brushed DC motor controllers

DRV8833 Dual Motor Driver Carrier



Logic

OUT2	FUNCTION
Z	Coast/fast decay
H	Reverse
L	Forward
L	Brake/slow decay

Brushed DC motor controllers

DRV8833 Dual Motor Driver Carrier

- $V_{IN} = 2.7-10.8V$
- 3V compatible inputs
- $I_{con} = 1.2A$ (per channel)
- $I_{peak} = 2A$ (per channel)
- Parallel couple two!

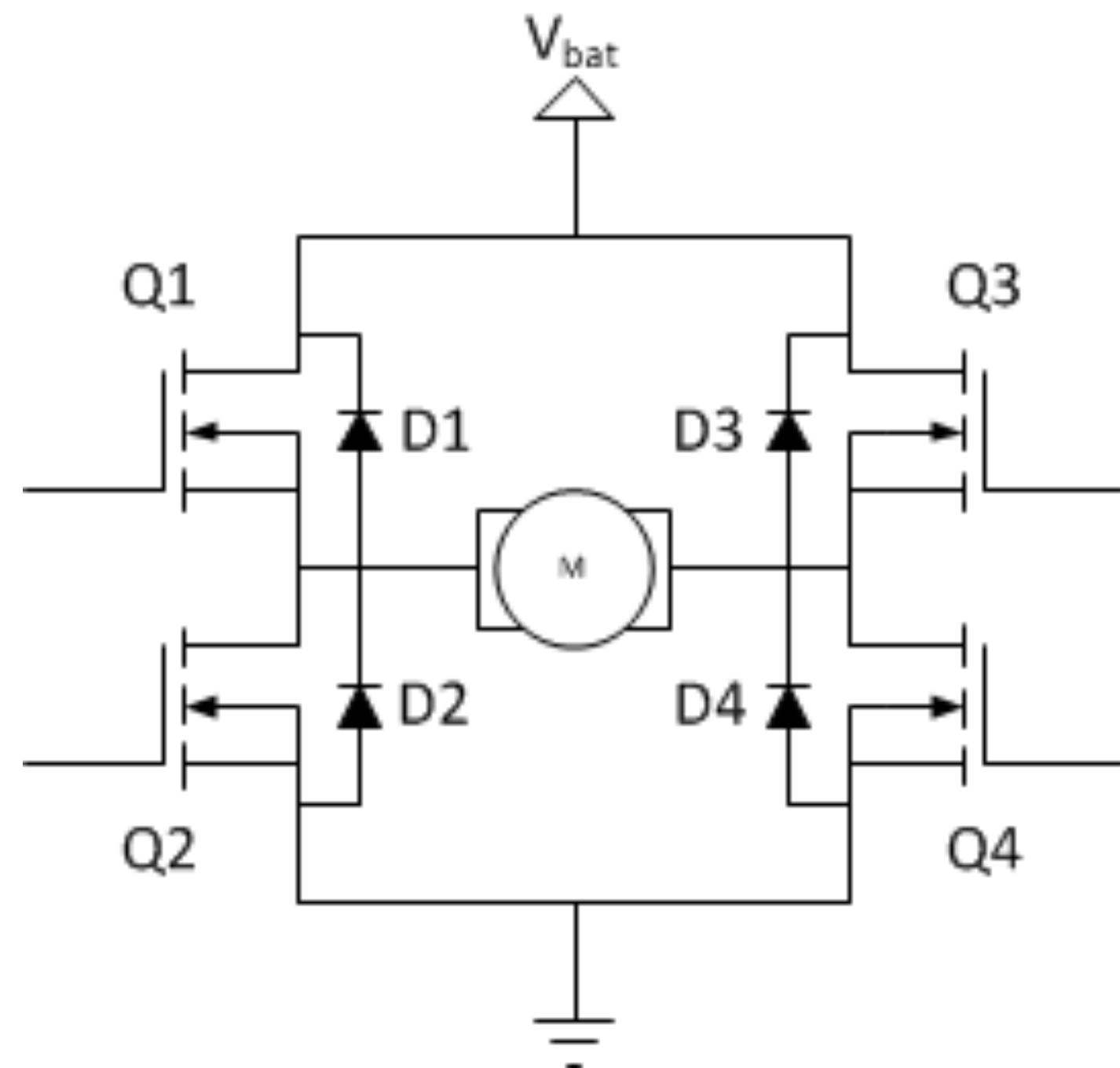
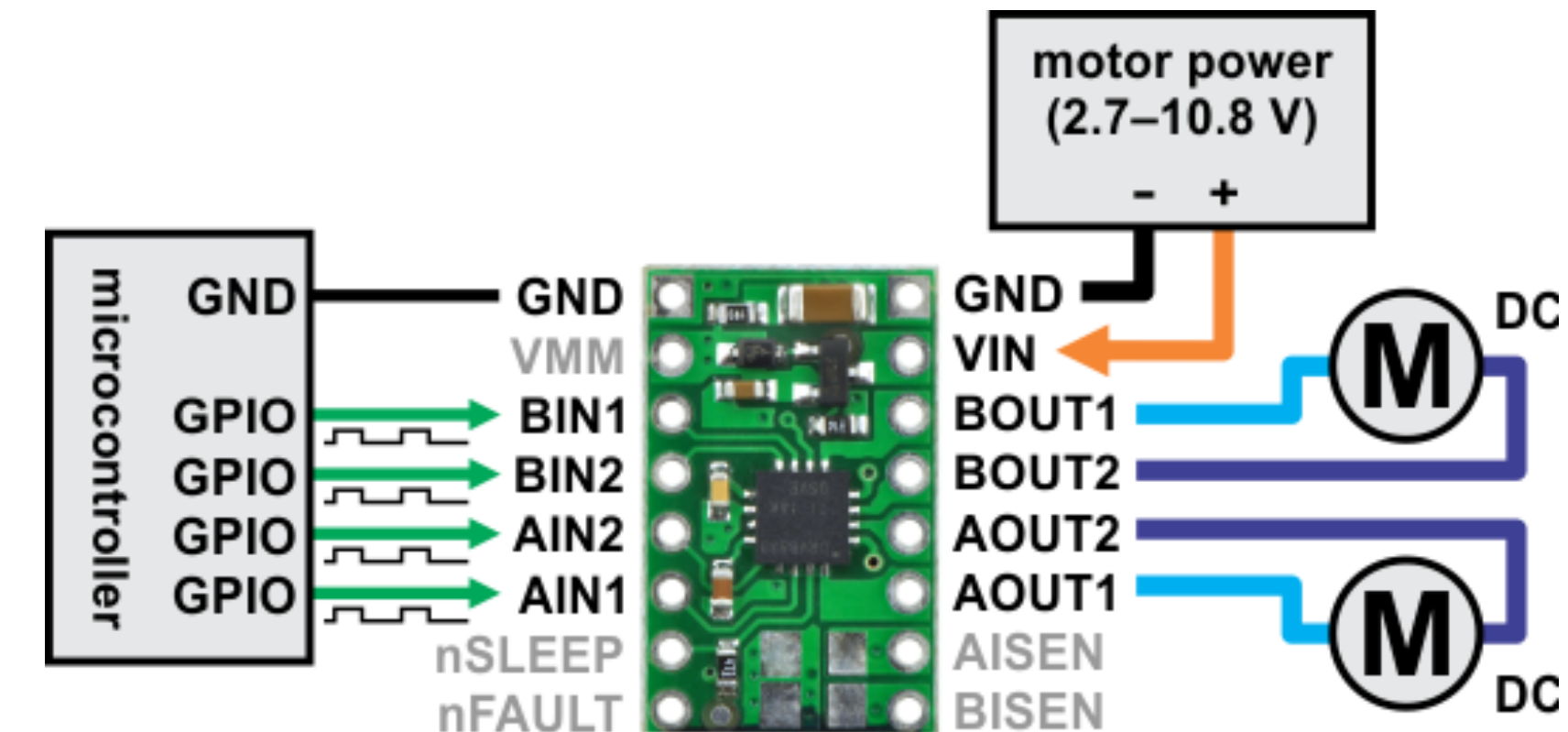
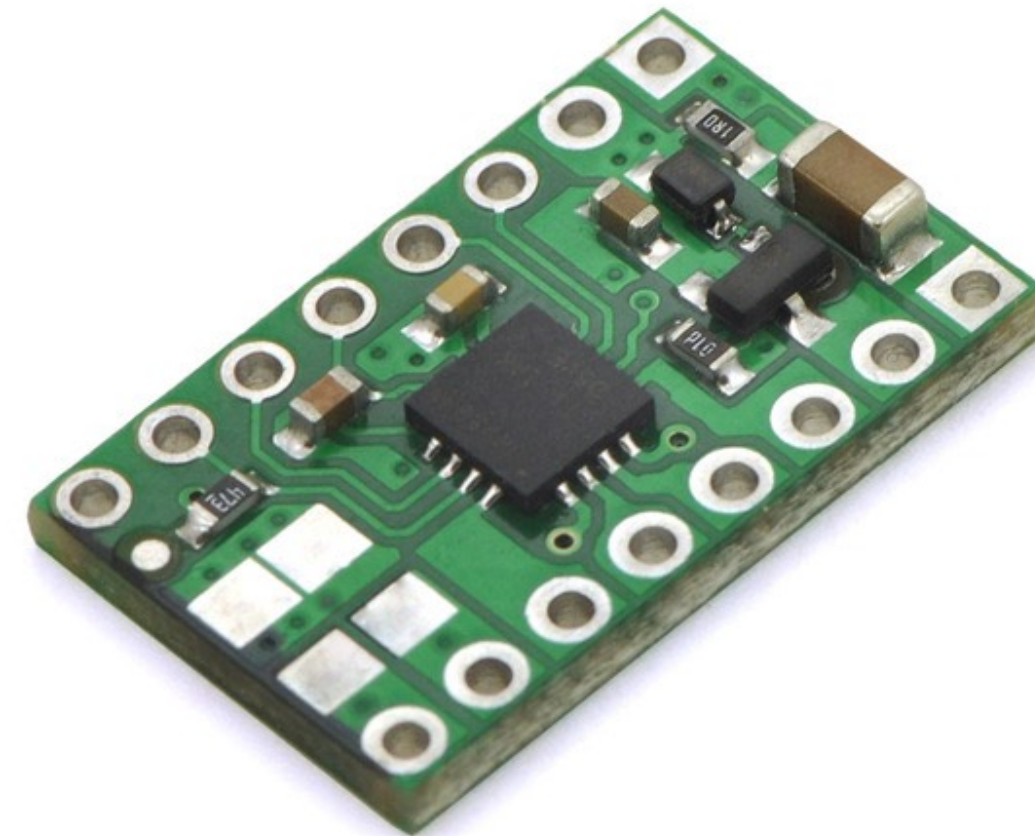
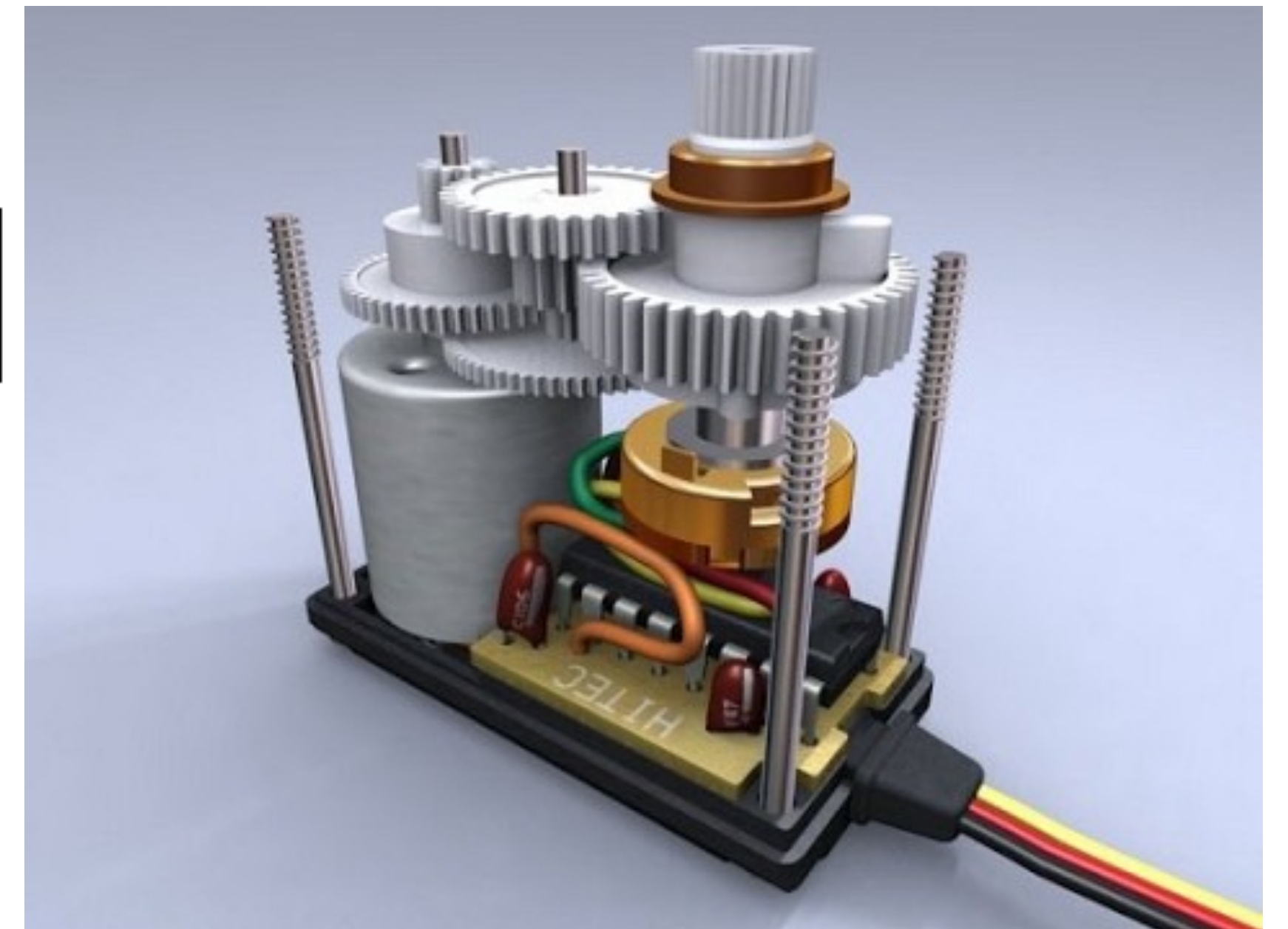
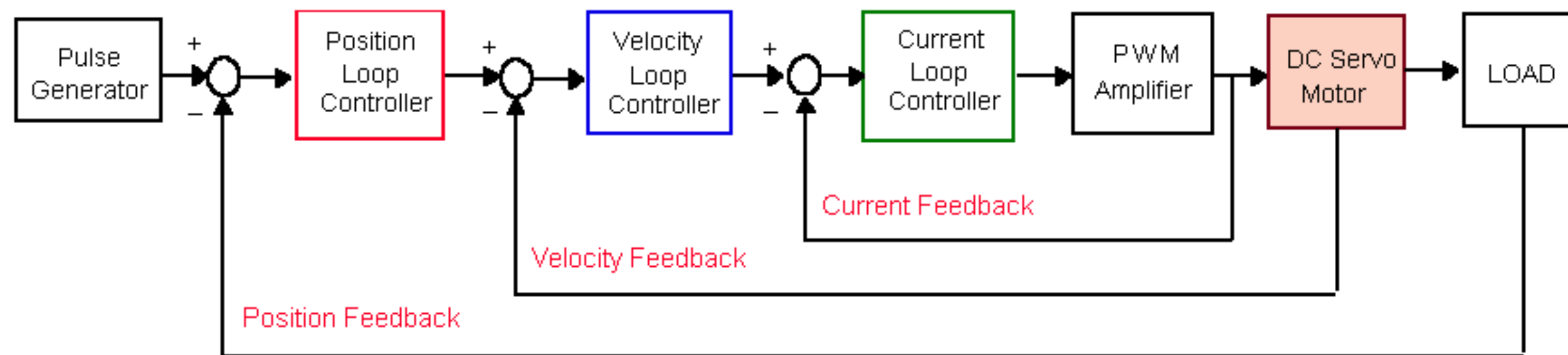
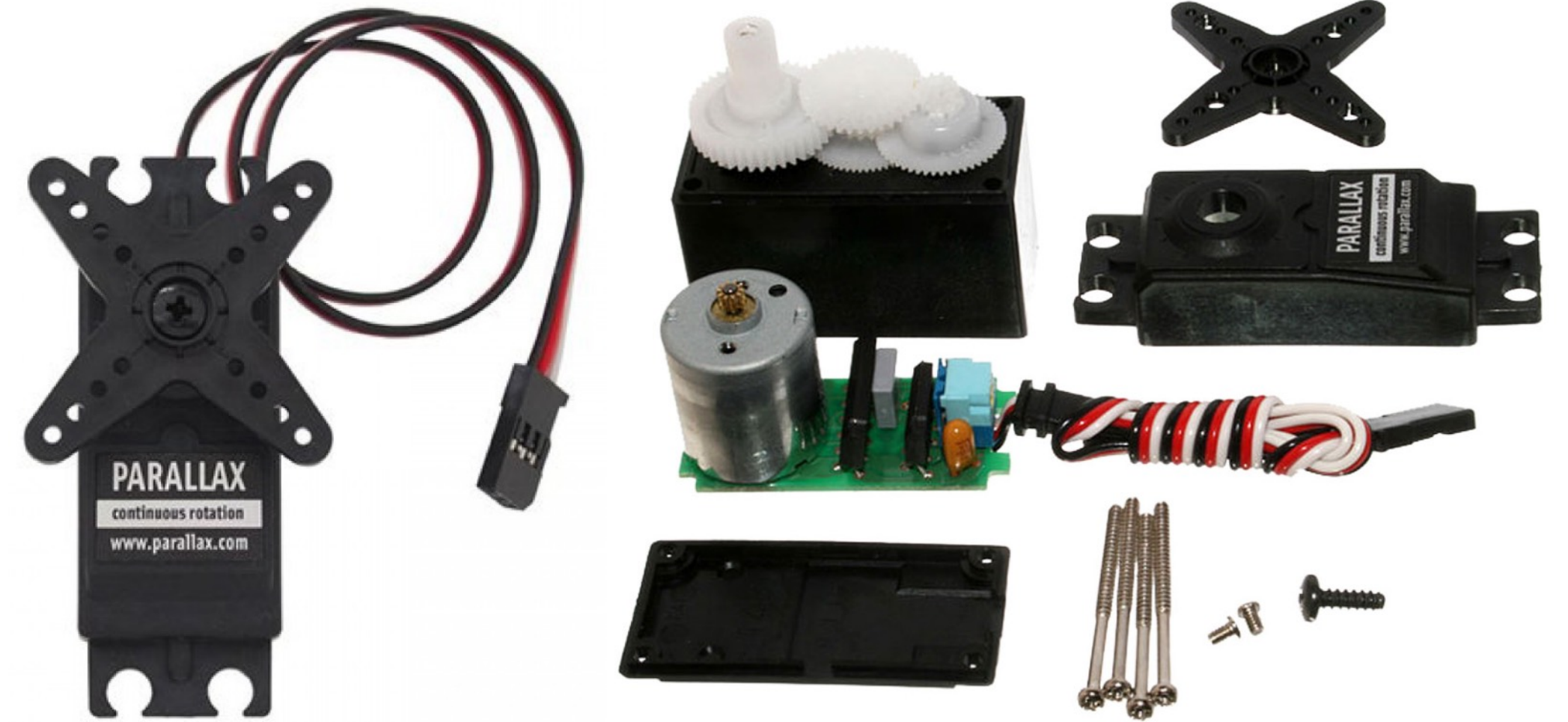


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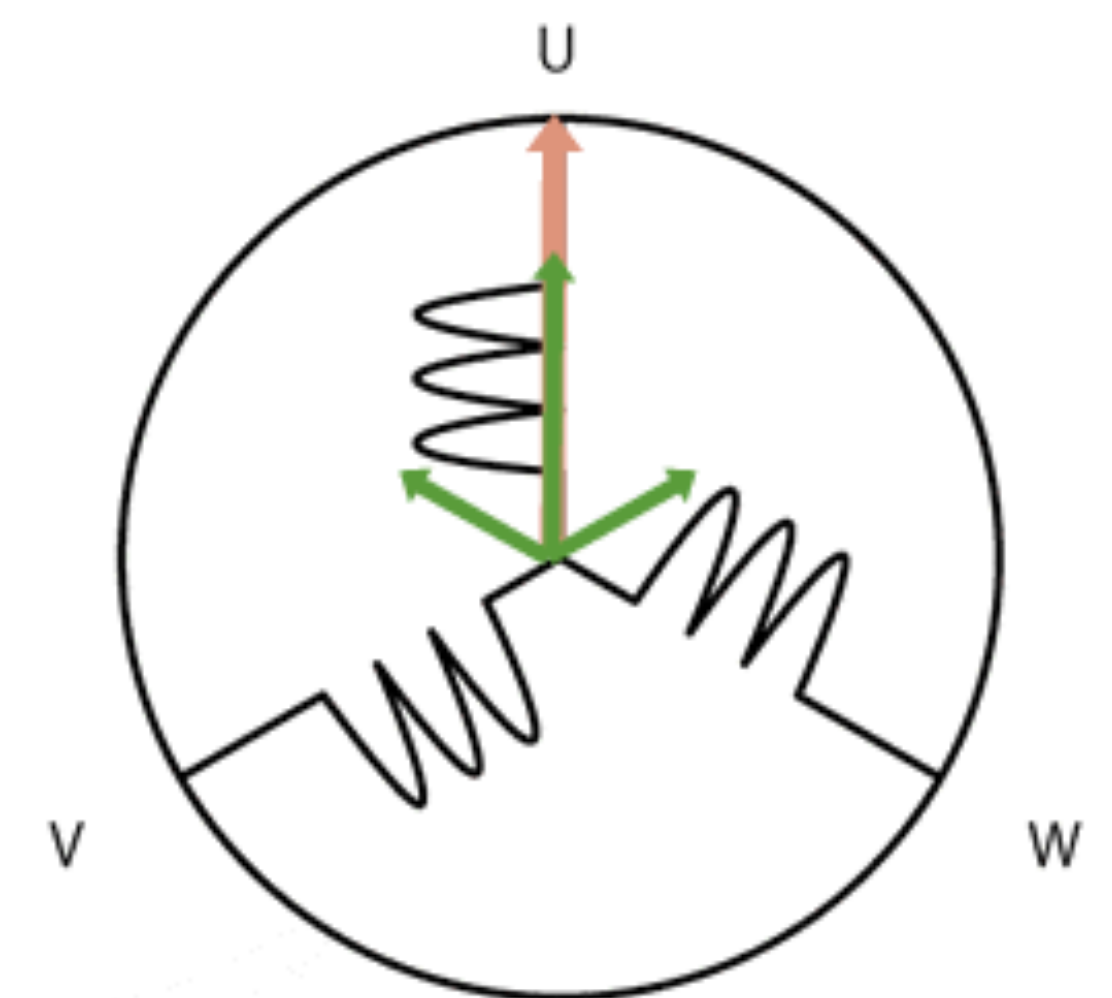
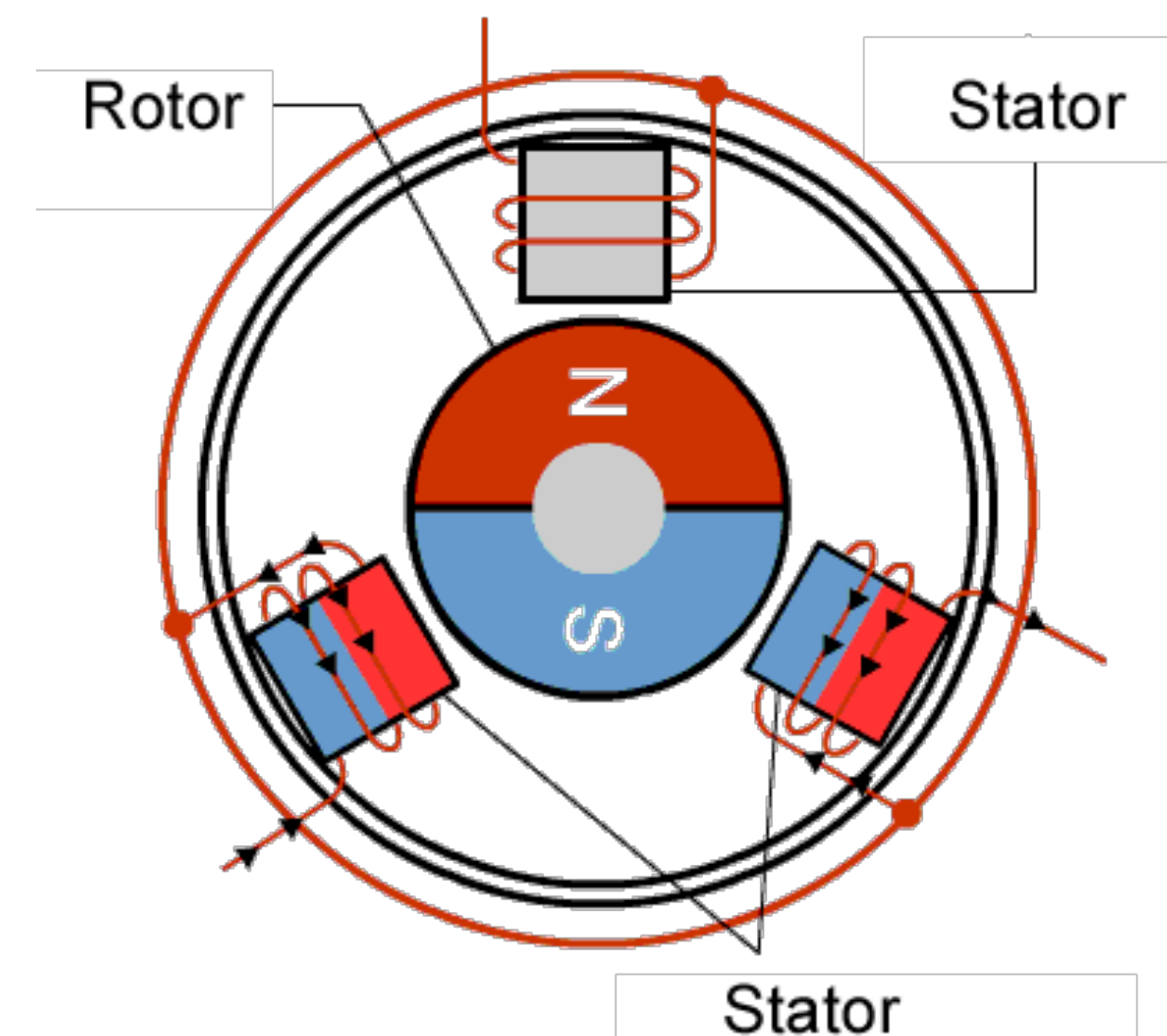
Servo motor

- Hobby-oriented PMDC motor
 - Duty cycle of a 50Hz 0-5V signal
- Continuous rotation servo
- Position controlled servo



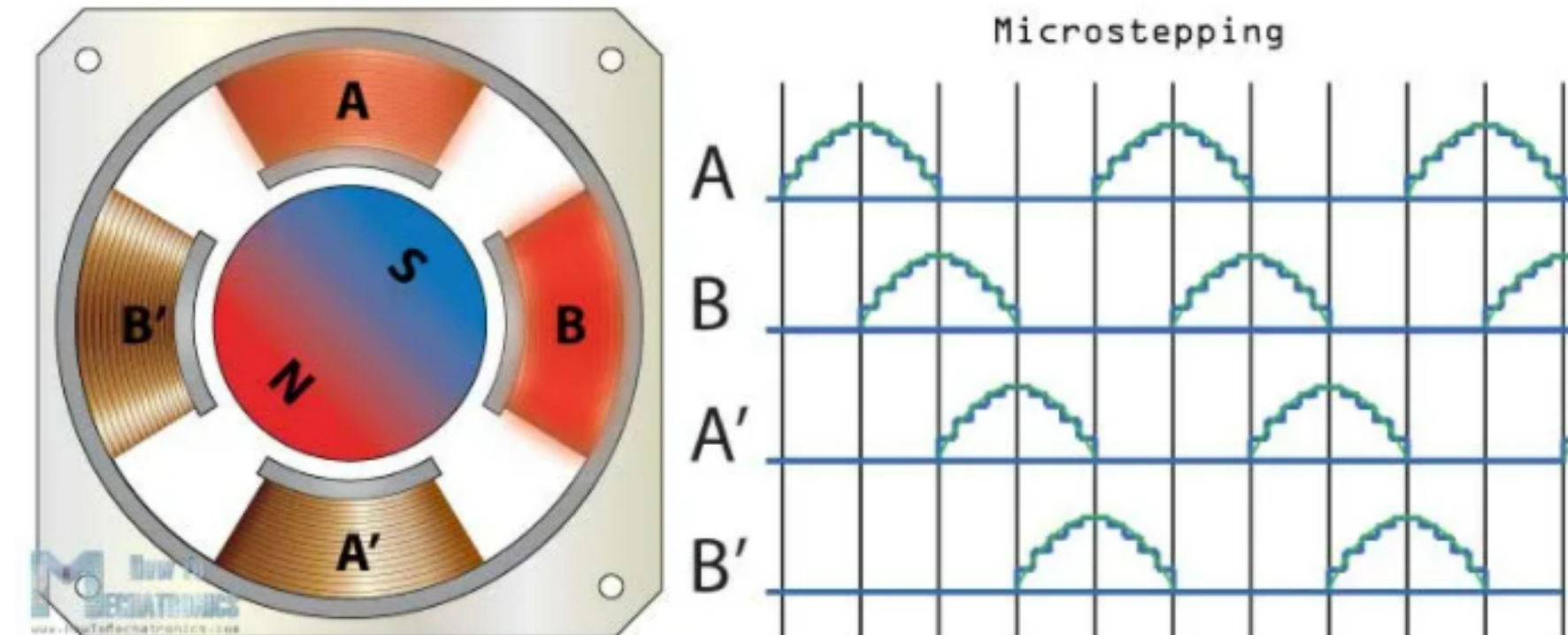
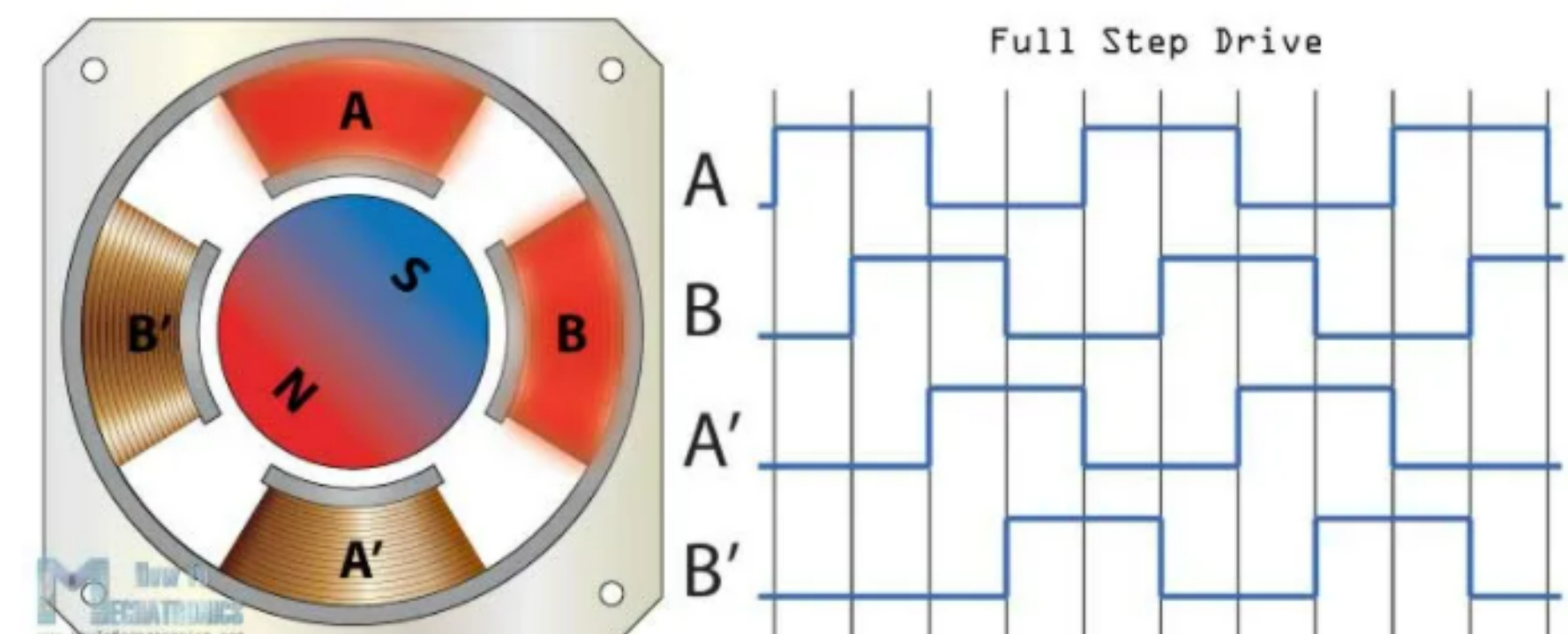
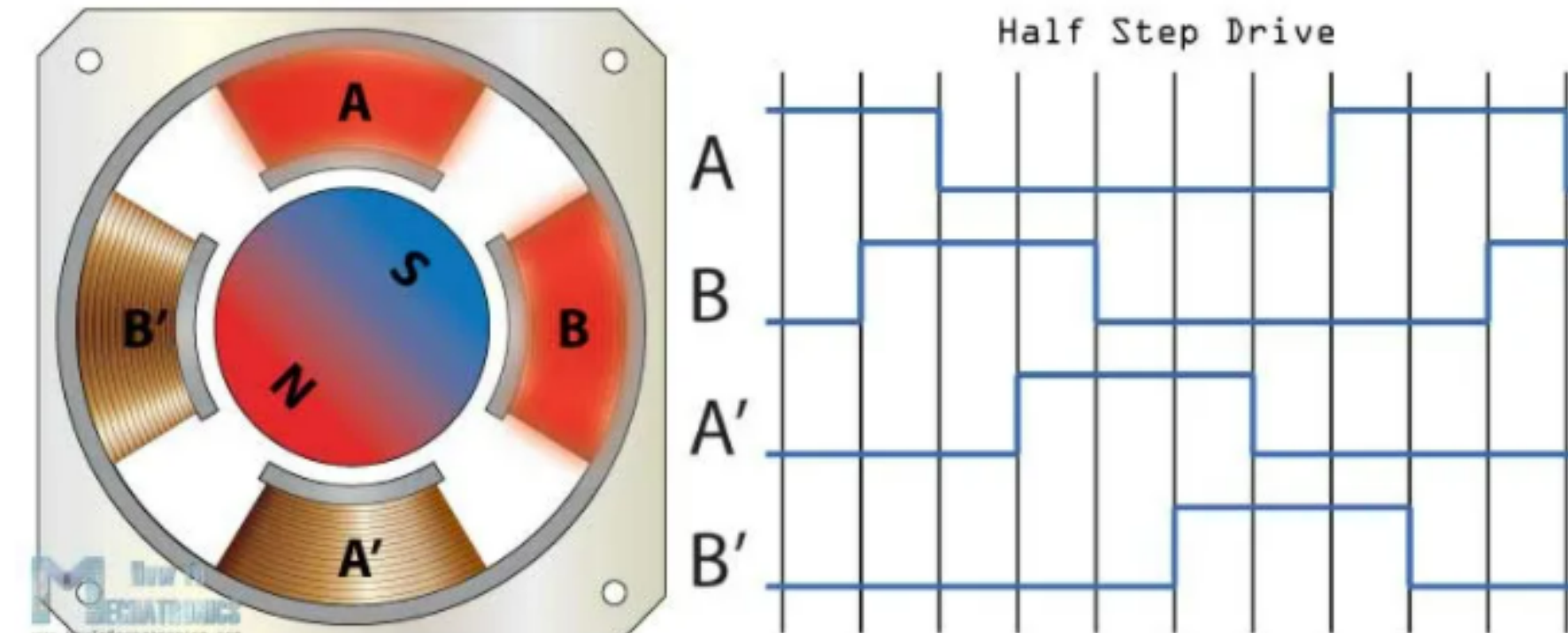
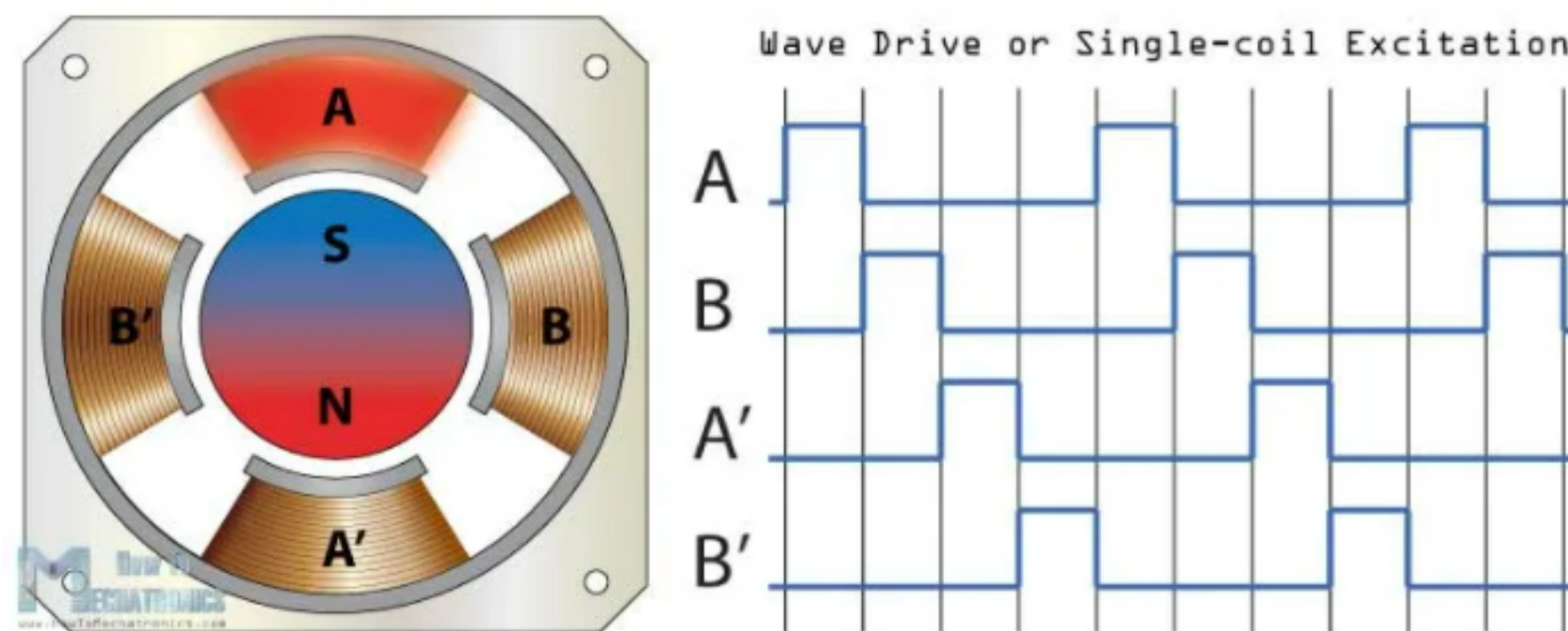
Brushless DC motor (BLDC)

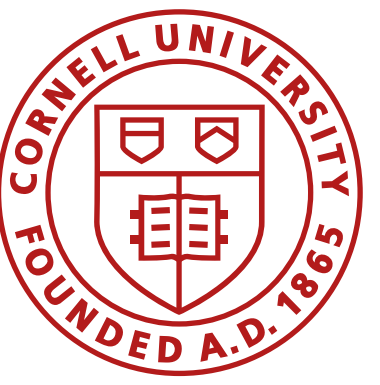
- Inside-out PMDC
- Higher efficiency (85-90% compared to 74-80% brushed)
- No wear, easier cooling, low EMI
- Higher power, high starting torque
- Precise control of torque and speed
 - Discrete control (easy, but jerky)
 - Sinusoidal control
- Position sensing
 - Sensors (hall effect, etc.)
 - Sensorless (back-EMF)
 - Lower speeds, worse control
 - Initialization



Stepper motor

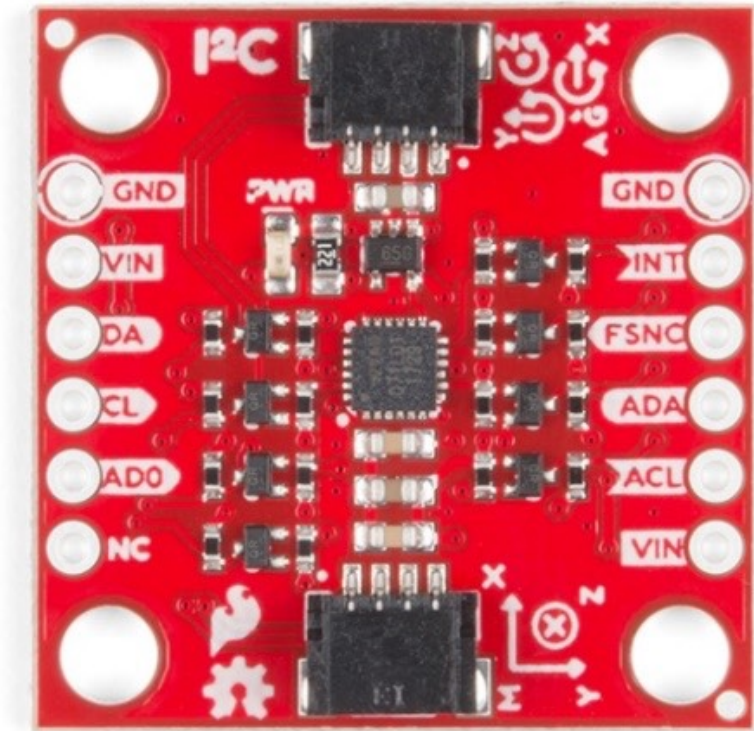
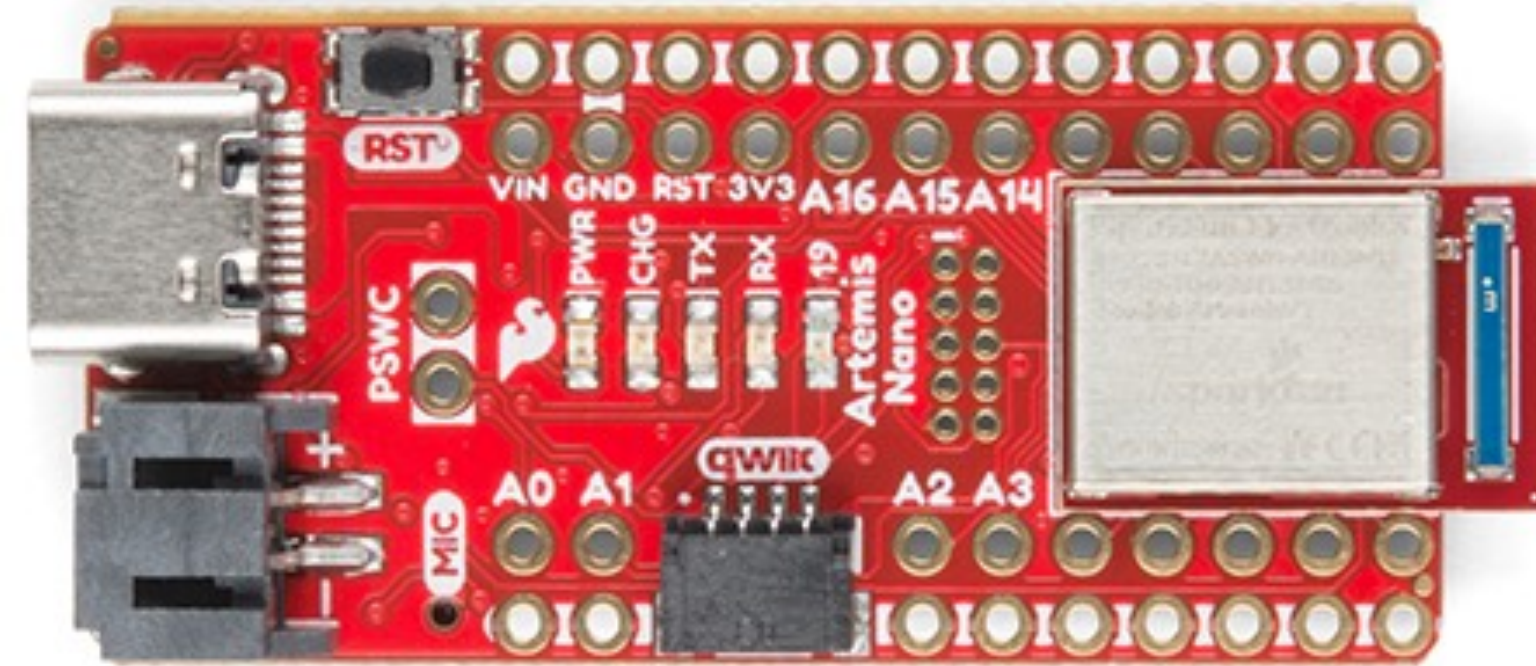
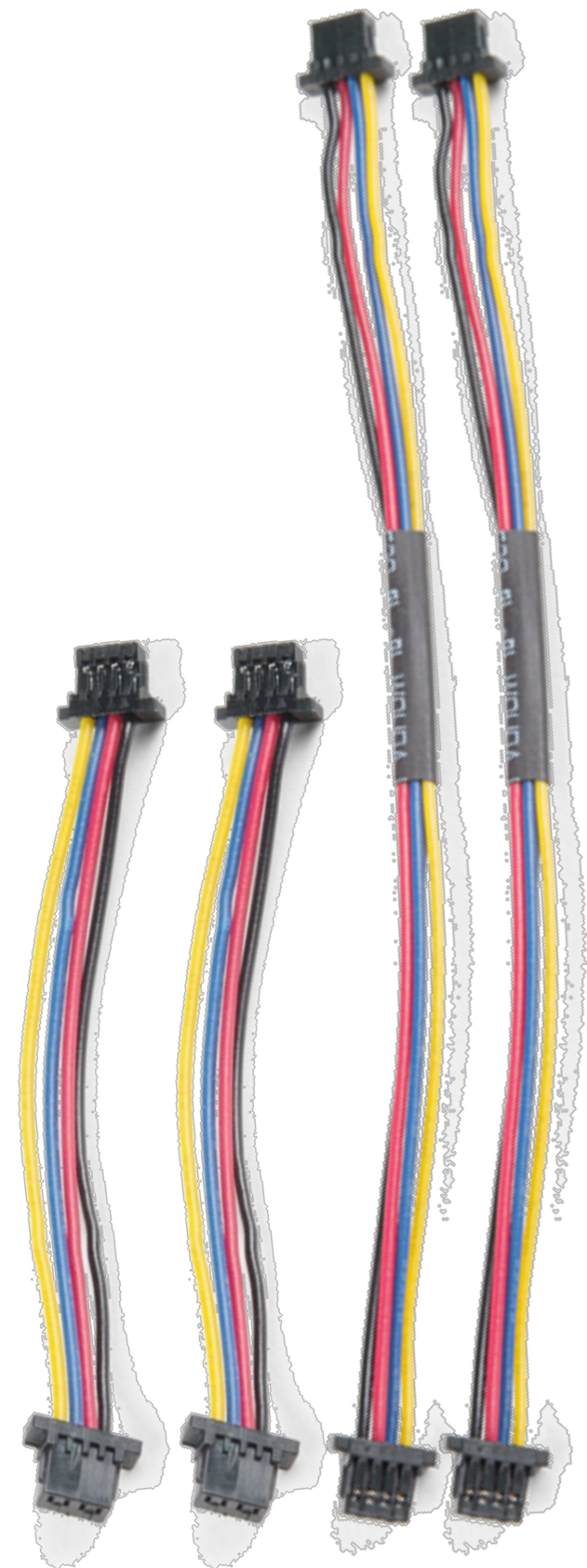
- Good choice when low speed and high precision is needed
- Advantages: high torque compared to servos, constant holding torque, frictionless
- Disadvantages: low efficiency, torque declines rapidly with speed, low torque to inertia



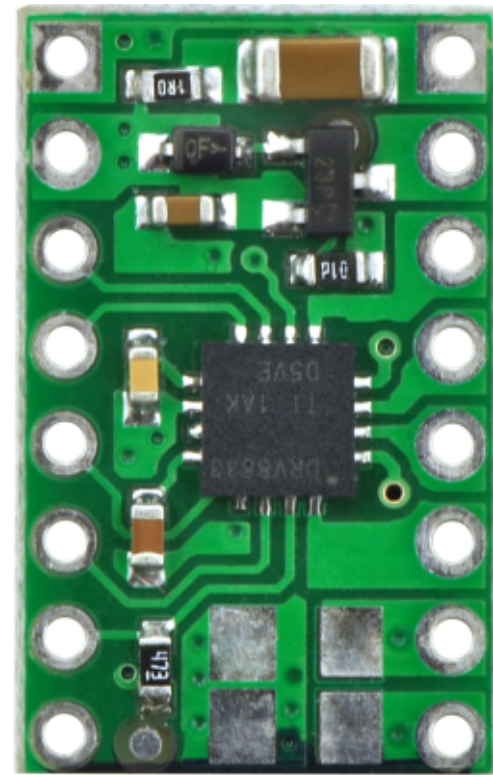


Labs 2-4: Hardware integration

Hardware

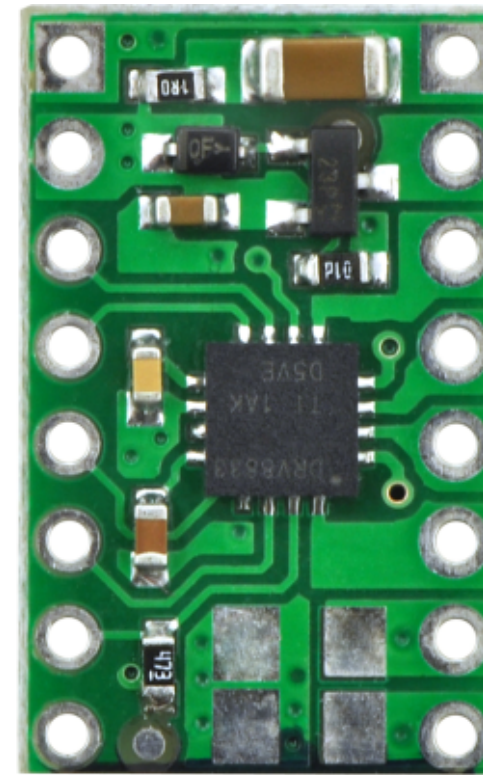


GND
VMM
BIN1
BIN2
AIN2
AIN1
nSLEEP
nFAULT



GND
VIN
BOUT1
BOUT2
AOUT2
AOUT1
AISEN
BISEN

GND
VMM
BIN1
BIN2
AIN2
AIN1
nSLEEP
nFAULT

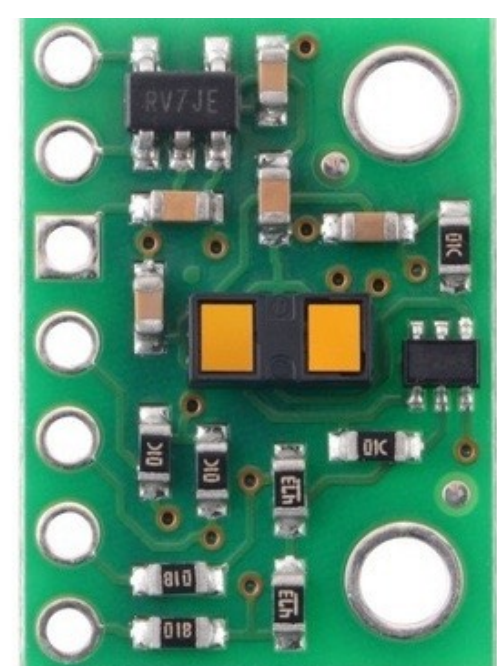


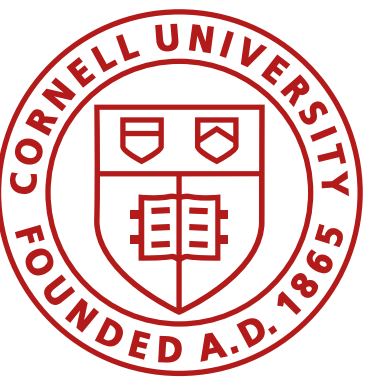
GND
VIN
BOUT1
BOUT2
AOUT2
AOUT1
AISEN
BISEN

VDD (2.8V out)
VIN (2.6–5.5V)
GND
SDA
SCL
XSHUT
GPIO1

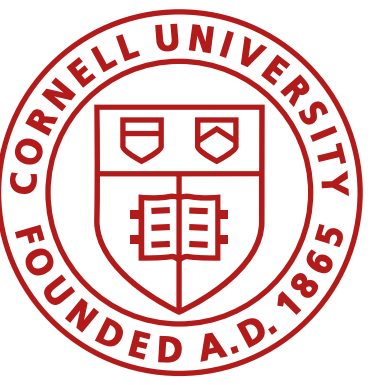


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GND
SDA
SCL
XSHUT
GPIO1

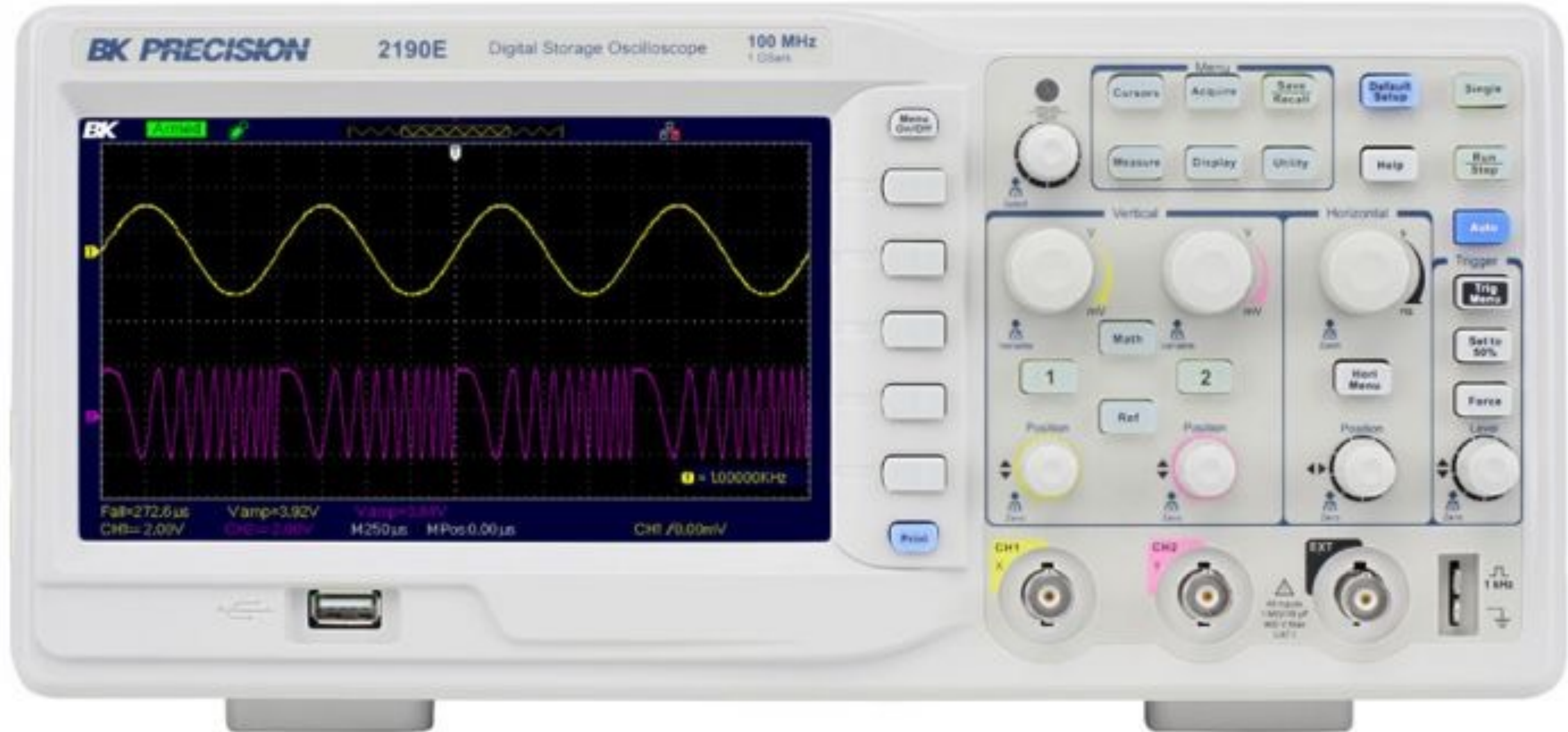


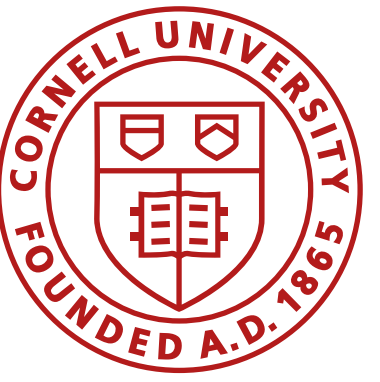


Oscilloscopes



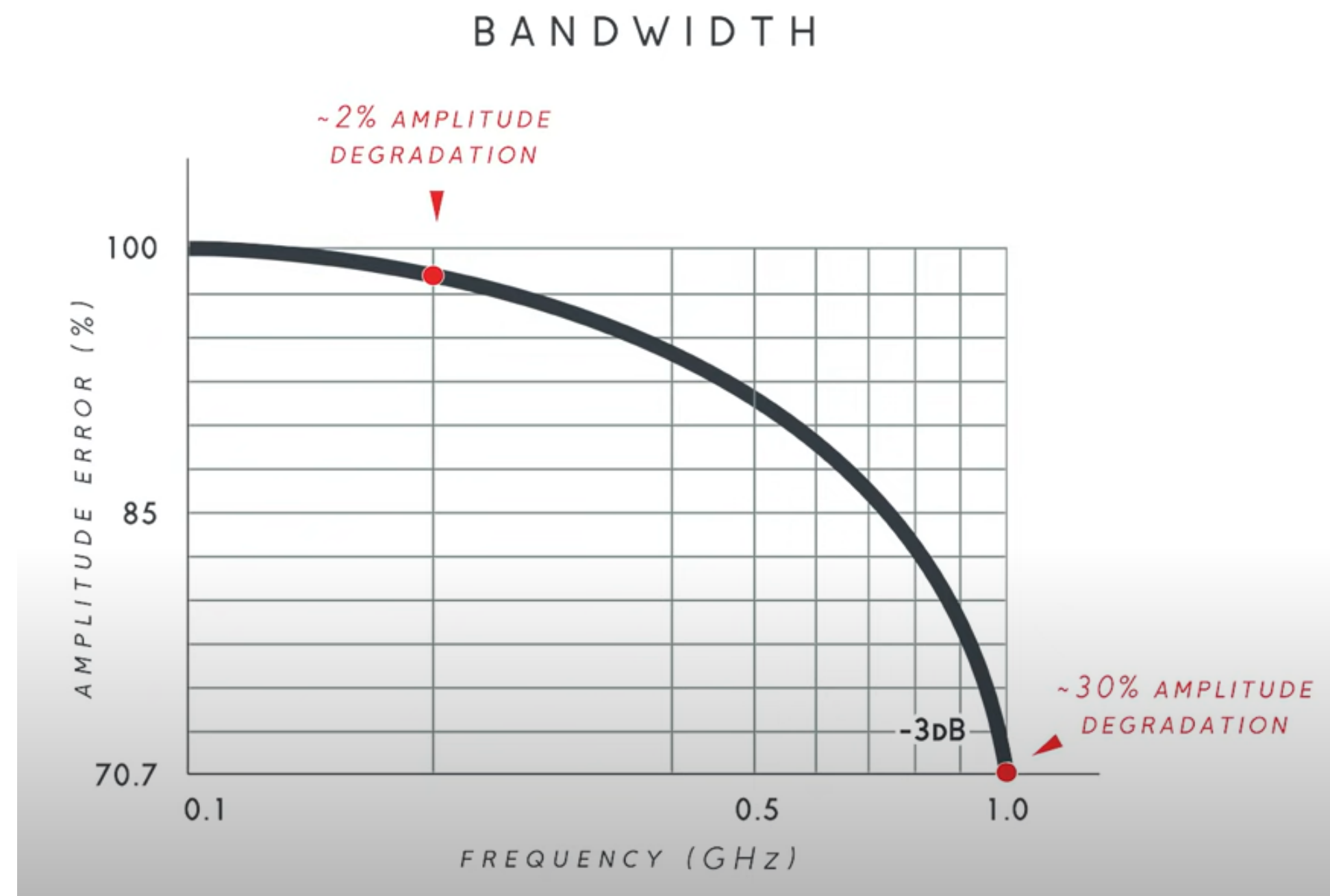
Oscilloscope setup



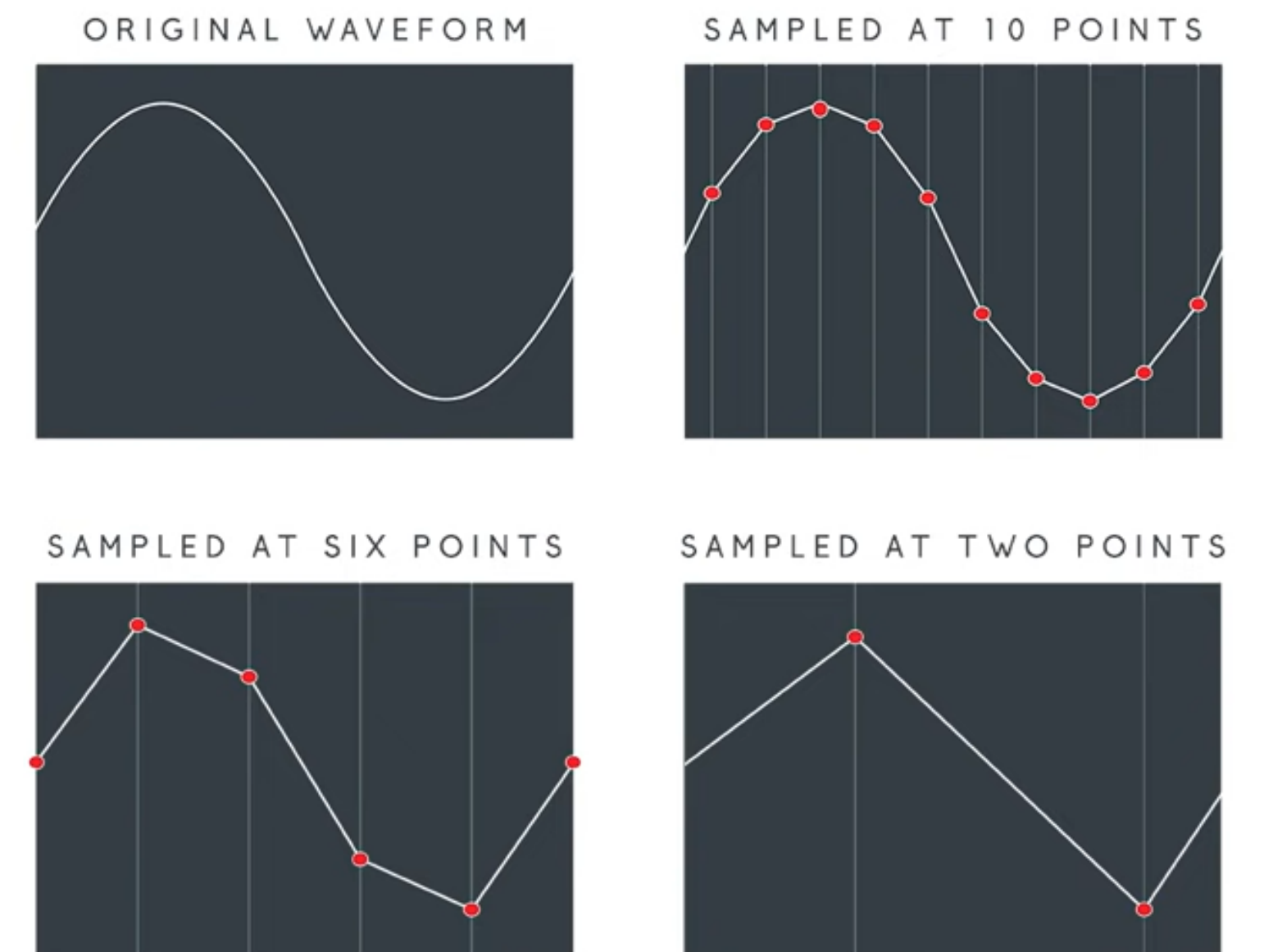


Oscilloscope setup

- Bandwidth
- Sample rate
- Resolution



SAMPLE RATE

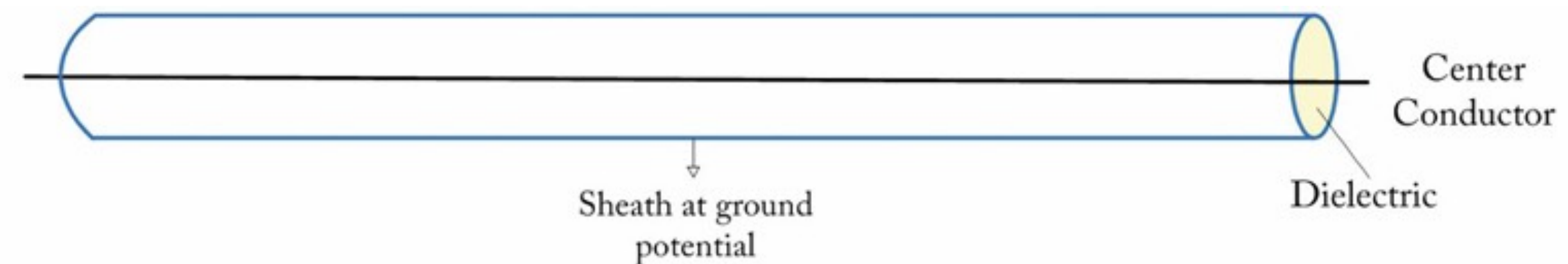


Oscilloscope Probes

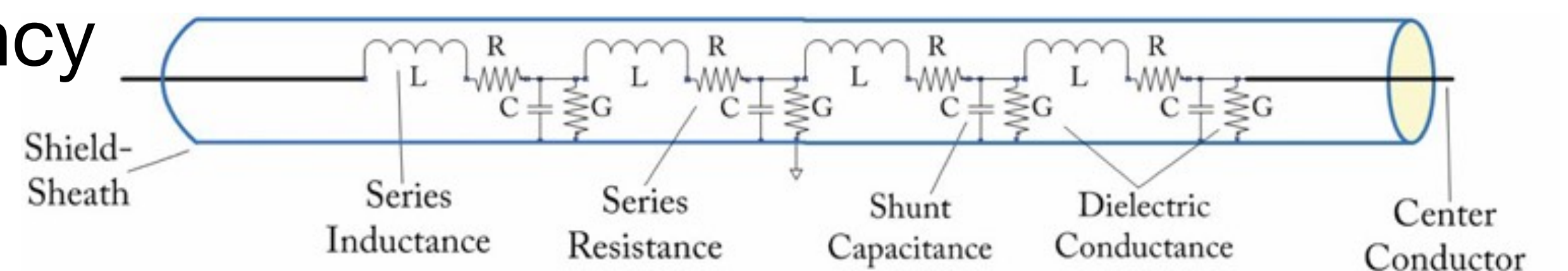
- Scope inputs resemble a 16pF capacitor in parallel with a 1M Ω resistor
- At high frequencies the coax cable acts as a low pass filter
- 1x attenuation for low amplitude, low frequency signals
- 10x attenuation for load-sensitive circuits, high-frequency or high-amplitude signals

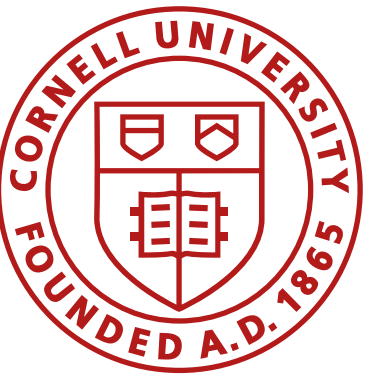


Low frequency
coax cable



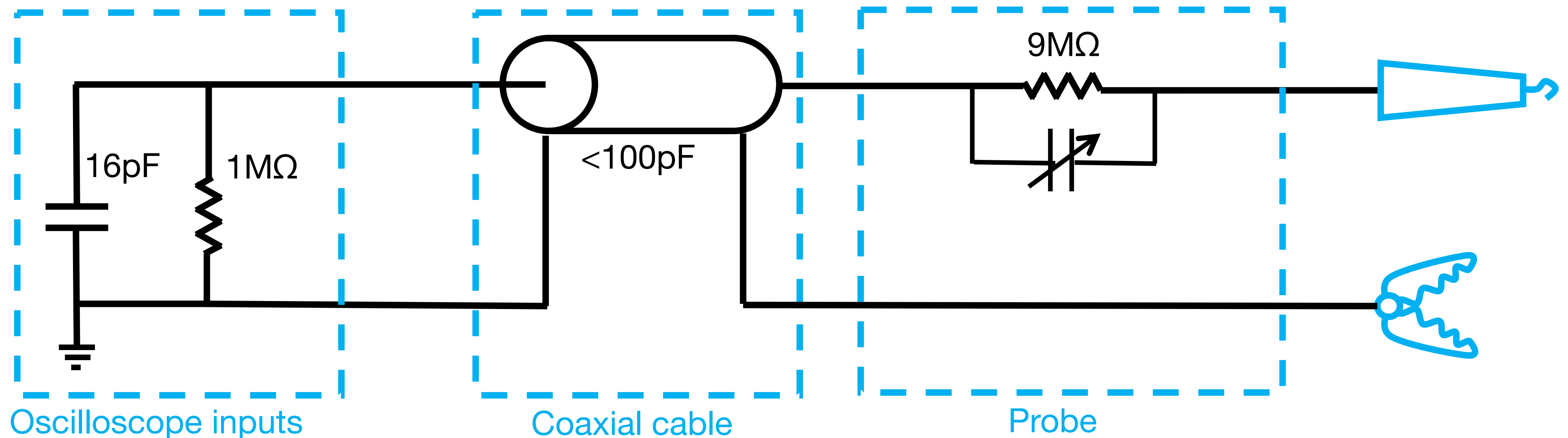
High frequency
circuit





Oscilloscope Probes

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Oscilloscope Probes

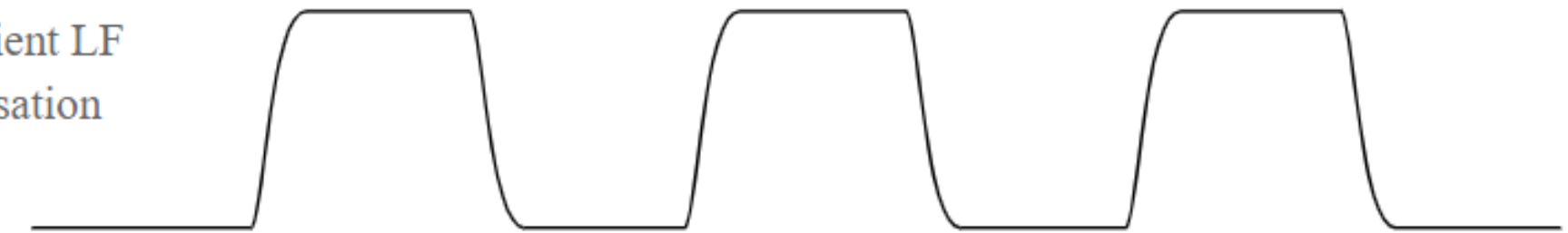
- 10x probe calibration
 - Use the built-in square wave generator
 - Adjust capacitor until the square wave looks square!



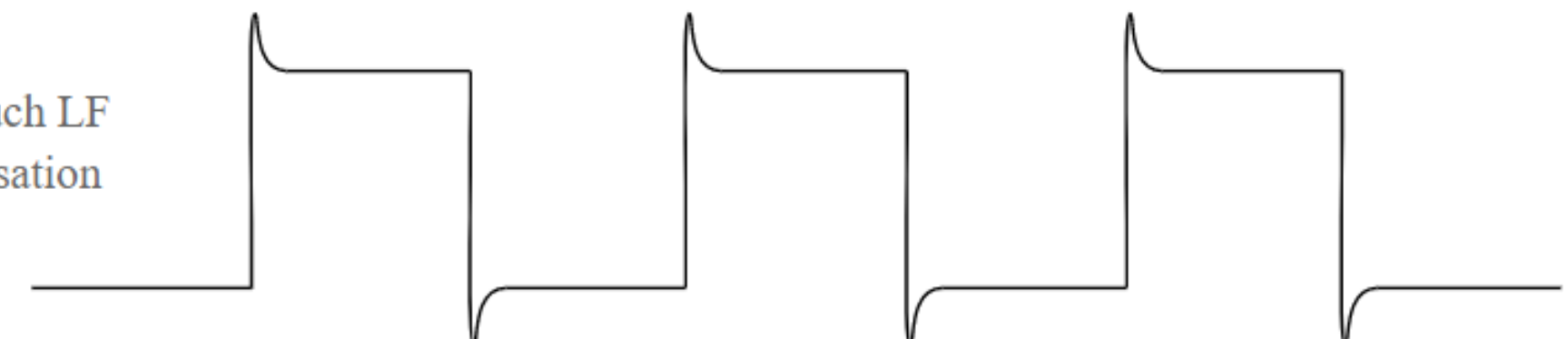
Required waveform display

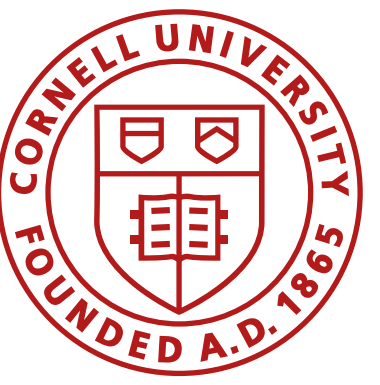


Insufficient LF compensation



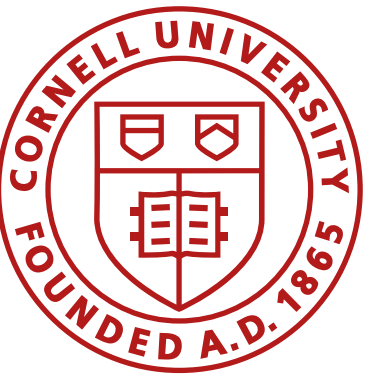
Too much LF compensation





Oscilloscope setup





Class Action Items

- Lab 2 is due Tuesday 8am for Lab 401, Wednesday 8am for Labs 402, 403
- If you choose to drop the class, please let me or the teaching staff know so you can give us back the kits!
- Check the calendar for open hours
- Feel free to charge your batteries in lab during lab times/ open hours as you feel comfortable.
- We are going to cut the cable on your 650mAh/ 750mAh batteries next lab so you can charge through the Artemis!